

# DSC 140A

*Probabilistic Modeling & Machine Learning*

Lecture 01 | Part 1

**Boosting**

# Today

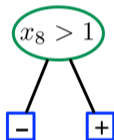
- ▶ Can we **combine** very **simple** models and get good results?
- ▶ **Yes: boosting.**

# Weak Learners

- ▶ A **weak classifier** is one which performs only a little better than chance.
- ▶ A learning algorithm capable of consistently producing weak classifiers is called a **weak learner**.
- ▶ Usually very simple, fast.

# Example

- ▶ A **decision stump** is a **weak classifier**.



- ▶ **Weak learner:** the strategy discussed last time for picking question.

# Example

- ▶ The full decision tree learning algorithm is a **strong learner**.

# The Question

- ▶ Can we “boost” the quality of a weak learner?

# Boosting: The Idea

- ▶ Train a weak classifier,  $H_1 : \mathcal{X} \rightarrow [-1, 1]$ .
- ▶ Increase weight (importance) of misclassified points, train another classifier  $H_2$ .
- ▶ Repeat, creating more classifiers, updating weights.
- ▶ Final classifier: a linear combination of  $H_1, \dots, H_k$ .

# The Details

- ▶ **Q1:** How do we measure the performance of a classifier on a weighted data set?
- ▶ **Q2:** How do we update the point weights?
- ▶ **Q3:** How do we combine the classifiers?



# AdaBoost

- ▶ Yoav Freund (UCSD) and Robert Schapire.
- ▶ A theoretically-sound answer to these questions.

# Q1: Measuring Performance

- ▶ Suppose weights at step  $t$  are in  $\vec{w}^{(t)}$ .
  - ▶ Assume normalized s.t. weights add to one.
- ▶ We use weights to learn a classifier  $H_t : \mathcal{X} \rightarrow [-1, 1]$ .
- ▶ The “margin”:

$$r_t = \sum_{i=1}^n \omega_i^{(t)} y_i H_t(\vec{x}^{(i)}) \in [-1, 1]$$

# Q1: Measuring Performance

- ▶ The **performance** of  $H_t$ :

$$\alpha_t = \frac{1}{2} \ln \frac{1 + r_t}{1 - r_t}$$

## Q2: Updating Weights

- ▶ We use weights to learn a classifier  $H_t : \mathcal{X} \rightarrow [-1, 1]$ .
- ▶ Weigh misclassified points more heavily.
- ▶ Point is misclassified if  $y_i H_t(\vec{x}^{(i)}) < 0$

## Q2: Updating Weights

- ▶ This will do the trick:

$$\omega_i^{(t+1)} \propto \omega_i^{(t)} \cdot \exp(-\alpha_t y_i H_t(\vec{x}^{(i)}))$$

- ▶  $\propto$  because we normalize.

## Q3: Combining Classifiers

- ▶ The final classifier:

$$H_t(\vec{X}) = \sum_{t=1}^T \alpha_t H_t(\vec{X})$$

# AdaBoost

Given data  $(\vec{x}^{(1)}, y_1), \dots, (\vec{x}^{(n)}, y_n)$ , labels in  $\{-1, 1\}$ .

- ▶ Initialize weight vector,  $\vec{\omega}^{(1)} = (\frac{1}{n}, \frac{1}{n}, \dots, \frac{1}{n})^T$
- ▶ Repeat:
  - ▶ Give data and weights  $\vec{\omega}^{(t)}$  to weak learner. Receive a classifier,  $H_t : \mathcal{X} \rightarrow \{-1, 1\}$  back.
  - ▶ Calculate “performance”,  $\alpha_t = \frac{1}{2} \ln \frac{1+r_t}{1-r_t}$
  - ▶ Update  $\vec{\omega}^{(t+1)} \propto \omega_i^{(t)} \cdot \exp(-\alpha_t y_i H_t(\vec{x}^{(i)}))$
- ▶ Final classifier:  $H_t(\vec{x}) = \sum_{t=1}^T \alpha_t H_t(\vec{x})$

# Example: Decision Stumps

- ▶ To learn decision stump, given data and  $\vec{\omega}^{(t)}$ .
- ▶ Try all features, thresholds.
- ▶ Choose that which maximizes the margin:

$$r_t = \sum_{i=1}^n \omega_i^{(t)} y_i H_t(\vec{x}^{(i)}) \in [-1, 1]$$

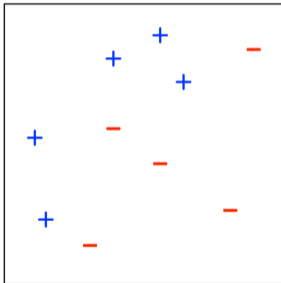


# Example: Decision Stumps

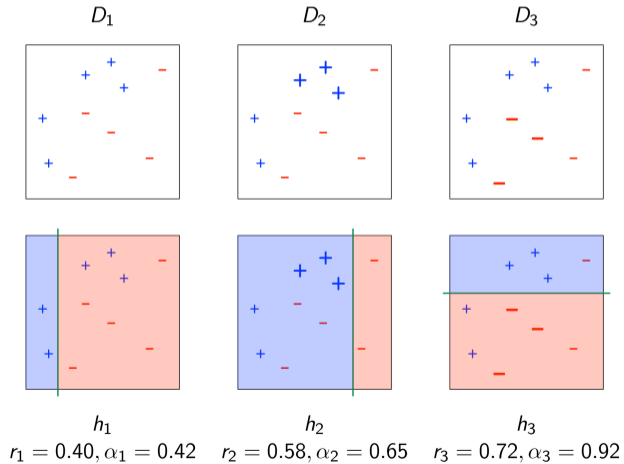
- ▶ To learn decision stump, given data and  $\vec{\omega}^{(t)}$ .
- ▶ Try all features, thresholds.
- ▶ Equivalently, choose that which maximizes the performance:

$$\alpha_t = \frac{1}{2} \ln \frac{1 + r_t}{1 - r_t}$$

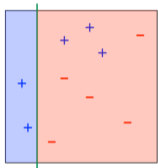
# Example



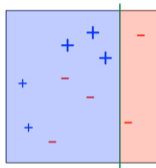
# Example



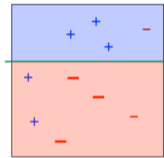
# Example



$h_1$   
 $\alpha_1 = 0.42$



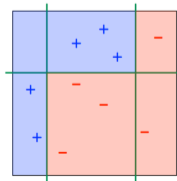
$h_2$   
 $\alpha_2 = 0.65$



$h_3$   
 $\alpha_3 = 0.92$

Final classifier:

$$\text{sign}(0.42h_1(x) + 0.65h_2(x) + 0.92h_3(x))$$

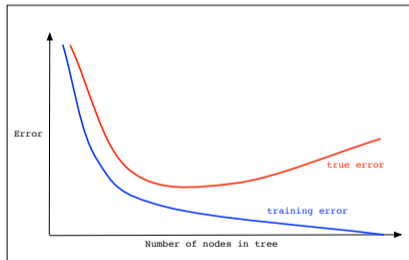


# Theory

Suppose that on each round  $t$ , the weak learner returns a rule  $H_t$  whose error on the step  $t$  weighted data is  $\leq \frac{1}{2} - \gamma$ . Then after  $T$  rounds, the training error of the combined rule  $H$  is at most  $e^{-\gamma^2 T/2}$ .

# Generalization

- ▶ Boosted decision stumps are really resistant to overfitting.



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# Why not?

- ▶ Why use weak learners?
- ▶ What if we replace decision stumps with SVMs or logistic regression?



# Why not?

- ▶ Why use weak learners?
- ▶ What if we replace decision stumps with SVMs or logistic regression?
- ▶ You can, but weak learners are **fast** to learn.
- ▶ The point of boosting is that weak learners are “just as good” as strong learners.

# DSC 140A

*Probabilistic Modeling & Machine Learning*

Lecture 01 | Part 2

**Random Forests**

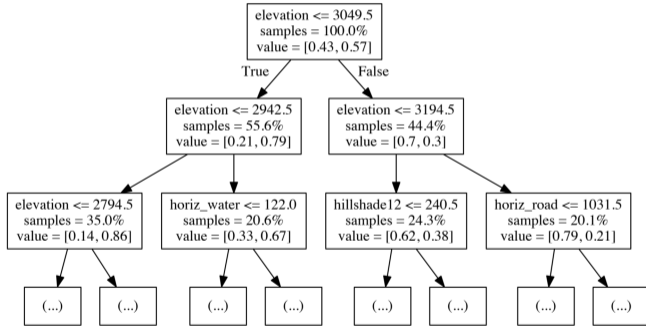
## Let's Try

- ▶ Decision trees are susceptible to overfitting.
- ▶ Let's try using boosted decision trees.

# Example: Forest Cover Type

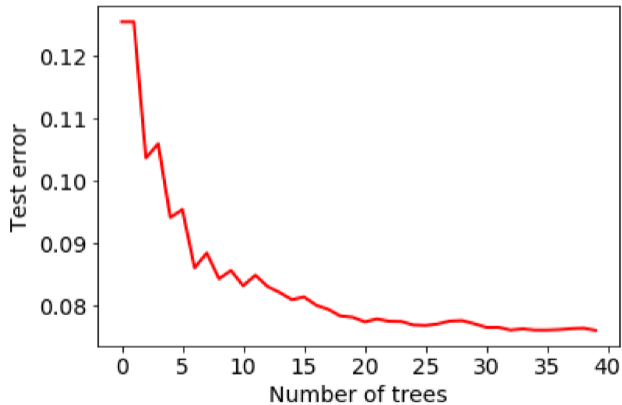
- ▶ **Goal:** predict forest type.
  - ▶ Spruce-fir
  - ▶ Lodgepole pine
  - ▶ etc. 7 classes in total.
- ▶ 54 cartographic/geological features.
  - ▶ Elevation, slope, amount of shade, distance to water, etc.

# Decision Tree

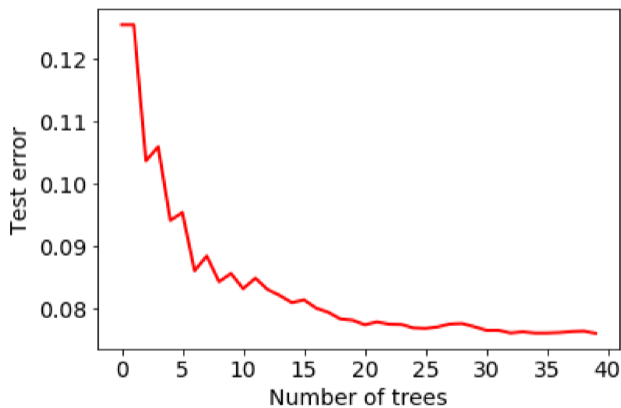


Depth 20. Training error: 1%. Test error: 12.6%.

# Boosted Decision Trees



# Boosted Decision Trees



Depth 20: Test error: 8.7%. **Slow!**

## Another Idea

- ▶ Prevent decision trees from overfitting by “hiding data” randomly.
- ▶ Train a bunch of trees, quickly.
- ▶ Average them to make a final prediction.



# Random Forests

- ▶ For  $t = 1$  to  $T$ 
  - ▶ Choose  $n'$  training points randomly, with replacement.
  - ▶ Fit a decision tree,  $H_t$ .
    - ▶ At each node, restrict to one of  $k$  features, chosen randomly.
- ▶ Final classifier: majority vote of  $H_1, \dots, H_T$ .
- ▶ Common settings:  $n' = n$  (bootstrap),  $k = \sqrt{d}$ .

# Forest Cover Type

- ▶ Decision trees: 12.6% error.
- ▶ Boosted decision trees: 8.7% error (but **slow!**)
- ▶ Random forests: 8.8% error.
  - ▶ 50% of features dropped.
  - ▶ Each individual tree  $H_1, \dots, H_t$  has test error around 15%.