

# DSC 190

DATA STRUCTURES & ALGORITHMS

Lecture 17 | Part 1

**Today's Lecture**

# Massive Sets

- ▶ You've collected 1 billion tweets.<sup>1</sup>
- ▶ **Goal:** given the text of a new tweet, is it already in the data set?

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<sup>1</sup>This is about two days of activity.

# Membership Queries

- ▶ We want to perform a **membership query** on a collection of strings.
- ▶ Hash tables support  $\Theta(1)$  membership queries.
- ▶ **Idea:** so let's use a hash table (Python: `set`).

## Problem: Memory

- ▶ How much memory would a **set** of 1 billion strings require?
- ▶ Assume average string has 100 ASCII characters.  
 $(8 \text{ bits per char}) \times (100 \text{ chars}) \times 1 \text{ billion} = 100 \text{ gigabytes}$
- ▶ That's way too large to fit in memory!

# Today's Lecture

- ▶ **Goal:** fast membership queries on massive data sets.
- ▶ Today's answer: **Bloom filters**.

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DATA STRUCTURES & ALGORITHMS

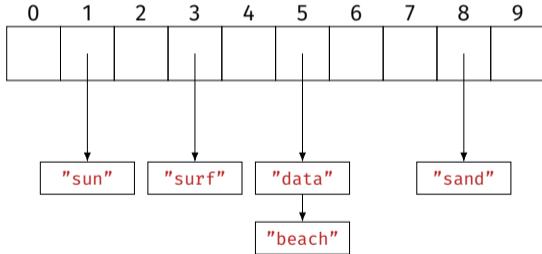
Lecture 17 | Part 2

**Bit Arrays**

# The Challenge

- ▶ We want to perform membership queries on a massive collection (too large to fit in memory).
- ▶ We want to remember which elements are in the collection...
- ▶ ...*without* actually storing all of the elements.
- ▶ From hash tables to Bloom filters in 3 steps.

# First Stop: Hash Tables



| s       | hash(s) |
|---------|---------|
| "surf"  | 3       |
| "sand"  | 8       |
| "data"  | 5       |
| "sun"   | 1       |
| "beach" | 5       |



# Memory Usage

- ▶ **Problem:** we're storing all of the elements.
- ▶ Why? To resolve collisions.
- ▶ **Fix:** ignore collisions.

## Second Stop: Hashing Into Bit Arrays

|   |   |   |   |   |   |   |   |   |   |
|---|---|---|---|---|---|---|---|---|---|
| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| 0 | 1 | 0 | 1 | 0 | 1 | 0 | 0 | 1 | 0 |

| s       | hash(s) |
|---------|---------|
| "surf"  | 3       |
| "sand"  | 8       |
| "data"  | 5       |
| "sun"   | 1       |
| "beach" | 5       |

- ▶ Use a bit array `arr` of size `c`.
- ▶ **Insertion:** Set  $\text{arr}[\text{hash}(x)] = 1$ .
- ▶ **Query:** Check if  $\text{arr}[\text{hash}(x)] = 1$ .

# Second Stop: Hashing Into Bit Arrays

|   |   |   |   |   |   |   |   |   |   |
|---|---|---|---|---|---|---|---|---|---|
| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| 0 | 1 | 0 | 1 | 0 | 1 | 0 | 0 | 1 | 0 |

| s       | hash(s) |
|---------|---------|
| "surf"  | 3       |
| "sand"  | 8       |
| "data"  | 5       |
| "sun"   | 1       |
| "beach" | 5       |

- ▶ Use a bit array `arr` of size `c`.
- ▶ **Insertion:** Set `arr[hash(x)] = 1`.
- ▶ **Query:** Check if `arr[hash(x)] = 1`.
- ▶ Can be **wrong!**

# False Positives

|   |   |   |   |   |   |   |   |   |   |
|---|---|---|---|---|---|---|---|---|---|
| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| 0 | 1 | 0 | 1 | 0 | 1 | 0 | 0 | 1 | 0 |

| s       | hash(s) |
|---------|---------|
| "surf"  | 3       |
| "sand"  | 8       |
| "data"  | 5       |
| "sun"   | 1       |
| "beach" | 5       |

- ▶ Query can return **false positives**.
- ▶ e.g.,  
`hash("ucsd") == 3`
- ▶ Cannot return false negatives.

# Memory Usage

- ▶ Requires  $c$  bits, where  $c$  is size of the bit array.
- ▶ False positive rate depends on  $c$ .
  - ▶  $c$  is small  $\rightarrow$  more collisions  $\rightarrow$  more errors
  - ▶  $c$  is large  $\rightarrow$  fewer collisions  $\rightarrow$  fewer errors
- ▶ **Tradeoff:** get more accuracy at cost of memory.

# False Positive Rate

- ▶ What is the probability of a false positive?
- ▶ Suppose there are  $c$  buckets, and we've inserted  $n$  elements so far.
- ▶ We query an object  $x$  that we haven't seen before.
- ▶ False positive  $\Leftrightarrow \text{arr}[\text{hash}(x)] == 1$ .

# False Positive Rate

- ▶ Assume **hash** assigns bucket uniformly at random.
  - ▶ If  $x \neq y$  then,  $\mathbb{P}(\text{hash}(x) = \text{hash}(y)) = 1/c$
- ▶ Prob. that first element does not collide with  $x$ :  $1 - 1/c$ .
- ▶ Prob. that first two do not collide:  $(1 - 1/c)^2$ .
- ▶ Prob. that all  $n$  elements do not collide:  $(1 - 1/c)^n$ .

# False Positive Rate

- ▶ Hint: for large  $z$ ,  $(1 - 1/z)^z \approx \frac{1}{e}$

- ▶ So the probability of no collision is:

$$(1 - 1/c)^n = [(1 - 1/c)^c]^{n/c} \approx e^{-n/c}$$

- ▶ This is the probability of no false positive.
- ▶ Probability of false positive upon querying  $x$ :  
 $\approx 1 - e^{-n/c}$



# False Positive Rate

- ▶ For fixed query, probability of false positive:  
 $\approx 1 - e^{-n/c}$ .
  - ▶  $n$ : number of elements stored
  - ▶  $c$ : size of array (number of bits)
- ▶ Randomness is over choice of hash function.
  - ▶ Once hash function is fixed, the result is always the same.

# Fixing False Positive Rate

- ▶ Suppose we'll tolerate false positive rate of  $\epsilon$ .
- ▶ Assume that we'll store around  $n$  elements.
- ▶ We can choose  $c$ :

$$1 - e^{-n/c} = \epsilon \quad \implies \quad c = -\frac{n}{\ln(1 - \epsilon)}$$

# Example

- ▶ Suppose we want  $\leq 1\%$  error.
- ▶ Previous slide says our bit array needs to be 100 times larger than number of elements stored.<sup>2</sup>
- ▶ Memory when  $n = 10^9$ : 1 billion bits  $\times 100 = 12.5$  GB.
- ▶ Can we do better?

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<sup>2</sup>We could have guessed this, huh?

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DATA STRUCTURES & ALGORITHMS

Lecture 17 | Part 3

**Bloom Filters**

# Wasted Space

- ▶ Suppose we want  $\leq 1\%$  error.
- ▶ Our bit array needs to be 100 times larger than number of elements stored.
- ▶ That's a lot of **wasted space!**

## Third Stop: Multiple Hashing

- ▶ **Idea:** use several smaller bit arrays, each with own hash function.

# Third Stop: Multiple Hashing

|   |   |   |   |   |   |   |   |   |   |
|---|---|---|---|---|---|---|---|---|---|
| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| 0 | 1 | 0 | 1 | 0 | 1 | 0 | 0 | 1 | 0 |
| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| 0 | 0 | 0 | 0 | 1 | 0 | 1 | 1 | 0 | 1 |

---

| s       | hash <sub>1</sub> (s) | hash <sub>2</sub> (s) |
|---------|-----------------------|-----------------------|
| "surf"  | 3                     | 7                     |
| "sand"  | 8                     | 7                     |
| "data"  | 5                     | 4                     |
| "sun"   | 1                     | 9                     |
| "beach" | 5                     | 6                     |

► Use  $k$  bit arrays of size  $c$ , each with own independent hash function.

► **Insertion:** Set  
 $\text{arr}_1[\text{hash}_1(x)] = 1,$   
 $\text{arr}_2[\text{hash}_2(x)] = 1,$   
...,  
 $\text{arr}_k[\text{hash}_k(x)] = 1.$

# Third Stop: Multiple Hashing

|   |   |   |   |   |   |   |   |   |   |
|---|---|---|---|---|---|---|---|---|---|
| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| 0 | 1 | 0 | 1 | 0 | 1 | 0 | 0 | 1 | 0 |
| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| 0 | 0 | 0 | 0 | 1 | 0 | 1 | 1 | 0 | 1 |

| s       | hash_1(s) | hash_2(s) |
|---------|-----------|-----------|
| "surf"  | 3         | 7         |
| "sand"  | 8         | 7         |
| "data"  | 5         | 4         |
| "sun"   | 1         | 9         |
| "beach" | 5         | 6         |

- ▶ Use  $k$  bit arrays of size  $c$ , each with own independent hash function.
- ▶ **Query:** Return **True** if **all** of
  - $\text{arr}_1[\text{hash}_1(x)] = 1$ ,
  - $\text{arr}_2[\text{hash}_2(x)] = 1$ ,
  - ...
  - $\text{arr}_k[\text{hash}_k(x)] = 1$ .
- ▶ Example:
  - $\text{hash}_1(\text{"hello"}) == 3$ ,
  - $\text{hash}_2(\text{"hello"}) == 2$



# Intuition

- ▶ False positive occurs only if false positive in **all** tables.
- ▶ This is pretty unlikely.
- ▶ If false positive rate in one table is small (but not tiny), probability false positive in all tables is still tiny.

## More Formally

- ▶ Probability of false positive in first table:  
 $\approx 1 - e^{-n/c}$ .
- ▶ Probability of false positive in all  $k$  tables:  
 $\approx (1 - e^{-n/c})^k$ .
- ▶ Example: if  $c = 4n$  and  $k = 3$ , error rate is  $\approx 1\%$ .
- ▶ Uses only  $12 \times n$  bits, as opposed to  $100 \times n$  from before.

# Last Stop: Bloom Filters

- ▶ How many different bit arrays do we use? (What is  $k$ ?)
- ▶ How large should they be? (What is  $c$ ?)
- ▶ **Bloom filters**: use  $k$  hash functions, but only one medium-sized array.

# Last Stop: Bloom Filters

|   |   |   |   |   |   |   |   |   |   |    |    |    |    |    |    |    |    |    |    |    |
|---|---|---|---|---|---|---|---|---|---|----|----|----|----|----|----|----|----|----|----|----|
| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 | 16 | 17 | 18 | 19 | 20 |
| 0 | 1 | 0 | 1 | 0 | 1 | 1 | 0 | 1 | 1 | 0  | 0  | 0  | 1  | 0  | 1  | 0  | 1  | 0  | 0  | 0  |

| s       | hash <sub>1</sub> (s) | hash <sub>2</sub> (s) |
|---------|-----------------------|-----------------------|
| "surf"  | 13                    | 17                    |
| "sand"  | 8                     | 6                     |
| "data"  | 15                    | 1                     |
| "sun"   | 1                     | 3                     |
| "beach" | 5                     | 9                     |

► Use one bit arrays of size  $c$ , but  $k$  hash functions.

► **Insertion:** Set  
 $\text{arr}[\text{hash}_1(x)] = 1,$   
 $\text{arr}[\text{hash}_2(x)] = 1,$   
...,  
 $\text{arr}[\text{hash}_k(x)] = 1.$

# Last Stop: Bloom Filters

|   |   |   |   |   |   |   |   |   |   |    |    |    |    |    |    |    |    |    |    |    |
|---|---|---|---|---|---|---|---|---|---|----|----|----|----|----|----|----|----|----|----|----|
| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 | 16 | 17 | 18 | 19 | 20 |
| 0 | 1 | 0 | 1 | 0 | 1 | 1 | 0 | 1 | 1 | 0  | 0  | 0  | 1  | 0  | 1  | 0  | 1  | 0  | 0  | 0  |

| s       | hash_1(s) | hash_2(s) |
|---------|-----------|-----------|
| "surf"  | 13        | 17        |
| "sand"  | 8         | 6         |
| "data"  | 15        | 1         |
| "sun"   | 1         | 3         |
| "beach" | 5         | 9         |

- ▶ Use one bit arrays of size  $c$ , but  $k$  hash functions.
- ▶ **Query:** Return **True** if **all** of  
 $\text{arr}[\text{hash}_1(x)] = 1$ ,  
 $\text{arr}[\text{hash}_2(x)] = 1$ ,  
...,  
 $\text{arr}[\text{hash}_k(x)] = 1$ .
- ▶ Example:  
 $\text{hash}_1(\text{"hello"}) == 3$ ,  
 $\text{hash}_2(\text{"hello"}) == 2$

# Intuition

- ▶ Multiple hashing allows bit arrays to be smaller.
- ▶ Even more efficient: let them share memory.
- ▶ “Overlaps” are just collisions; we can handle them.

# False Positive Rate

- ▶ Consider querying new, unseen object  $x$ .
- ▶ We'll look at  $k$  bits.
  - ▶  $arr[hash\_1(x)], \dots, arr[hash\_k(x)]$ .
- ▶ Fix one bit. What is the chance that it is already one?

# False Positive Rate

- ▶ Probability of bit being zero after first element inserted:  $(1 - 1/c)^k$
- ▶ After second element inserted:  $(1 - 1/c)^{2k}$
- ▶ After all  $n$  elements inserted:  $(1 - 1/c)^{nk}$
- ▶ And:

$$(1 - 1/c)^{nk} = [(1 - 1/c)^c]^{nk/c} \approx e^{-nk/c}$$



# False Positive Rate

- ▶ Probability of bit being **one** after  $n$  elements inserted:

$$1 - e^{-nk/c}$$

- ▶ For a false positive, all  $k$  bits (for each hash function) need to be one.
- ▶ Assuming independence,<sup>3</sup> probability of false positive:

$$(1 - e^{-nk/c})^k$$

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<sup>3</sup>Only true approximately. If this bit was set, some other bit was not.

# Minimizing False Positives

- ▶ For a fixed  $n$  and  $c$ , the number of hash functions  $k$  which minimizes the false positive rate is

$$k = \frac{c}{n} \ln 2$$

- ▶ Plugging this into the error rate:

$$\varepsilon = (1 - e^{-nk/c})^k \quad \implies \quad \ln \varepsilon = -\frac{c}{n} (\ln 2)^2$$

- ▶ If we fix  $\varepsilon$ , then  $c = -n \ln \varepsilon / (\ln 2)^2$

# Summary: Designing Bloom Filters

- ▶ Suppose we wish to store  $n$  elements with  $\epsilon$  false positive rate.
- ▶ Allocate a bit array with  $c = -n \ln \epsilon / (\ln 2)^2$  bits.
- ▶ Pick  $k = \frac{c}{n} \ln 2$  hash functions.

# Example

- ▶ Let  $n = 10^9$ ,  $\epsilon = 0.01$ .
- ▶ We need  $c \approx 9.5n \rightarrow 10n$  bits = 1.25 GB.
- ▶ We choose  $k = \frac{9.5n}{n} \ln 2 \rightarrow 7$  hash functions.

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DATA STRUCTURES & ALGORITHMS

Lecture 17 | Part 4

**Bloom Filters in Practice**

# Applications

- ▶ A cool data structure.
- ▶ Most useful when data is huge or memory is small.

# Application #1

- ▶ De-duplicate 1 billion strings, each about 100 bytes.
- ▶ Memory required for `set`: 100 gigabytes.
- ▶ Instead:
  - ▶ Loop through data, reading one string at a time.
  - ▶ If not in Bloom filter, write it to file.
- ▶ With 1% error rate, takes 1.25 GB.

## Application #2

- ▶ A ***k*-mer** is a substring of length *k* in a DNA sequence:

"GATTACATATAGGTGTCGA"

- ▶ Useful: does a long string have a given *k*-mer?
- ▶ There are a *massive* number of possible *k*-mers.
  - ▶  $4^k$ , to be precise.
  - ▶ Example: there are over  $10^{18}$  30-mers.
- ▶ Slide window of size *k* over sequence, store each substring in Bloom filter.



## Application #2

- ▶ Human genome is a 725 Megabyte string, 2.9 billion characters.
- ▶ To store all  $k$ -mers, each character stored  $k$  times.
- ▶ Storing 30-mers in **set** would take  $30 \times 725 \text{ MB} \approx 22 \text{ GB}$ .
- ▶ By “forgetting” the actual strings, Bloom filter (1% false positive) takes

2.9 billion bits  $\approx$  360 megabytes

# Application #3

- ▶ Suppose you have a massive database on disk.
- ▶ Querying the database will take a while, since it has to go to disk.
- ▶ Build a Bloom filter, keep in memory.
  - ▶ If Bloom filter says  $x$  not in database, don't perform query.
  - ▶ Otherwise, perform DB query.
- ▶ Speeds up time of “misses”.

# Limits

- ▶ Bloom filters are useful in certain circumstances.
- ▶ But they have disadvantages:
  - ▶ Need good idea of size,  $n$ , ahead of time.
  - ▶ There are false positives.
  - ▶ The elements are not stored (can't iterate over them).
- ▶ Often a **set** does just fine, with some care.

# Example

- ▶ Suppose you have 1 billion tweets.
- ▶ Want to de-duplicate them by **tweet ID** (64 bit number).
- ▶ Total size: 8 gigabytes.
- ▶ I have 4 GB RAM. Should I use a Bloom filter?

# De-duplication Strategy

- ▶ Design a hash function that maps each tweet ID to  $\{1, \dots, 8\}$ .
- ▶ Loop through tweet IDs one-at-a-time, hash, write to file:  
`hash(x) == 3 → write to data_3.txt`
- ▶ Read in each file, one-at-a-time, de-duplicate with `set`, write to `output.txt`