Lecture 15 – Clustering



DSC 40A, Fall 2022 @ UC San Diego

Dr. Truong Son Hy, with help from many others

Announcements

- Midterm this Friday!
- You can use a cheatsheet.

Agenda

- ▶ The k-Means clustering algorithm.
- Why does k-Means work?
- Practical considerations.

Question: how might we "cluster" these points into groups?



x1

Problem statement: clustering

Goal: Given a list of *n* data points, stored as vectors in \mathbb{R}^d , $\vec{x}_1, \vec{x}_2, ..., \vec{x}_n$, and a positive integer *k*, **place the data points into** *k* **groups of nearby points**.

- These groups are called "clusters".
- ► Think about groups as **colors**.
 - i.e., the goal of clustering is to assign each point a color, such that points of the same color are close to one another.
- Note, unlike with regression, there is no "right answer" that we are trying to predict — there is no y!
 - Clustering is an unsupervised method.

How do we define a group?

One solution: pick k cluster centers, i.e. centroids:

 $\mu_1,\mu_2,...,\mu_k$

- ► These *k* centroids define the *k* groups.
- Each data point "belongs" to the group corresponding to the nearest centroid.
- This reduces our problem from being "find the best group for each data point" to being "find the best locations for the centroids".

How do we define a group?



How do we pick the centroids?

- Let's come up with an cost function, C, which describes how good a set of centroids is.
 - Cost functions are a generalization of empirical risk functions.
- One possible cost function:

 $C(\mu_1, \mu_2, ..., \mu_k)$ = total squared distance of each data point \vec{x}_i to its closest centroid μ_i

- This C has a special name, inertia.
- Lower values of C lead to "better" clusterings.
 - **Goal:** Find the centroids $\mu_1, \mu_2, ..., \mu_k$ that minimize C.

Discussion Question

٠d

Suppose we have *n* data points, $\vec{x}_1, \vec{x}_2, ..., \vec{x}_n$, each of which are in \mathbb{R}^d .

Suppose we want to cluster our dataset into *k* clusters. How many ways can I assign points to clusters?

A)
$$d \cdot k$$

B) d^k
C) n^k
D) k^n
E) $n \cdot k$

Discussion Question

Suppose we have *n* data points, $\vec{x}_1, \vec{x}_2, ..., \vec{x}_n$, each of which are in \mathbb{R}^d .

Suppose we want to cluster our dataset into *k* clusters. How many ways can I assign points to clusters?

Answer: D

How do we minimize inertia?

- Problem: there are exponentially many possible clusterings. It would take too long to try them all.
- Another Problem: we can't use calculus or algebra to minimize C, since to calculate C we need to know which points are in which clusters.
- We need another solution.

k-Means Clustering, i.e. Lloyd's Algorithm

Here's an algorithm that attemps to minimize inertia:

- 1. Pick a value of *k* and randomly initialize *k* centroids.
- Keep the centroids fixed, and update the groups.
 Assign each point to the nearest centroid.
- 3. Keep the groups fixed, and update the centroids.
 Move each centroid to the center of its group.
- 4. Repeat steps 2 and 3 until the centroids stop changing.

Example

See the following site for an interactive visualization of k-Means Clustering: https://allisonhorst.com/k-means-clustering (shared by Suraj)

An example by-hand

Suppose we choose the initial centroids $\mu_1 = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$ and $\mu_2 = \begin{bmatrix} 3 \\ 4 \end{bmatrix}$.

Where will the centroids move to after one iteration of k-Means Clustering?



Follow along with the demo by clicking the **code** link on the course website next to Lecture 15.

Summary: K-Means clustering

Goal: Given a list of *n* data points, stored as vectors in \mathbb{R}^d , $\vec{x}_1, \vec{x}_2, ..., \vec{x}_n$, and a positive integer *k*, **place the data points into** *k* **clusters of nearby points**.

- ► Clusters are defined by **centroids**, $\mu_1, \mu_2, ..., \mu_k$. Each data point "belongs" to the group corresponding to the nearest centroid.
- We want to find the centroids that minimize inertia:

 $C(\mu_1, \mu_2, ..., \mu_k)$ = total squared distance of each data point \vec{x}_i to its closest centroid μ_i

k-Means Clustering is an algorithm that attempts to minimize inertia.

Summary: Lloyd's Algorithm

- 1. Pick a value of *k* and randomly initialize *k* centroids.
- Keep the centroids fixed, and update the groups.
 Assign each point to the nearest centroid.
- 3. Keep the groups fixed, and update the centroids.
 - Move each centroid to the center of its group by averaging their coordinates.
- 4. Repeat steps 2 and 3 until the centroids stop changing.

Why does k-Means work?

What is the goal of k-Means Clustering?

Recall, our goal is to find the centroids $\mu_1, \mu_2, ..., \mu_k$ that minimize inertia:

$$C(\mu_1, \mu_2, ..., \mu_k) = \text{ total squared distance of each}$$

data point \vec{x}_i to its
closest centroid μ_i

- Let's argue that each step of the k-Means Clustering algorithm reduces inertia.
 - After enough iterations, inertia will be small enough.

Why does k-Means work? (Step 1)

Let's look at each step one at a time.

Step 1: Pick a value of *k* and randomly initialize *k* centroids.

After initializing our k centroids, we have an initial value of inertia. We are going to argue that this only decreases.

Why does k-Means work? (Step 2)

Step 2: Keep the centroids fixed, and update the groups by assigning each point to the nearest centroid.

- Assuming the centroids are fixed, for each x_i we have a choice — which group should it be a part of?
- Whichever group we choose, inertia will be calculated using the squared distance between \vec{x}_i and that group's centroid.
- Thus, to minimize inertia, we assign each \vec{x}_i to the group corresponding to the closest centroid.

Note that this analysis holds every time we're at Step 2, not just the first time.

Why does k-Means work? (Step 3)

- **Step 3**: Keep the groups fixed, and update the centroids by moving each centroid to the center of its group (by averaging coordinates).
 - Before we justify why this is optimal, let's re-visit inertia.

Aside: separating inertia

Inertia:

 $C(\mu_1, \mu_2, ..., \mu_k)$ = total squared distance of each data point \vec{x}_i to its closest centroid μ_i

Note that an equivalent way to write inertia is

$$C(\mu_1, \mu_2, ..., \mu_k) = C(\mu_1) + C(\mu_2) + ... + C(\mu_k) \text{ where}$$
$$C(\mu_j) = \text{total squared distance of each}$$
$$\text{data point } \vec{x}_i \text{ in group } j$$
$$\text{to centroid } \mu_j$$

What's the point?

Why does k-Means work? (Step 3)

$$\begin{split} C(\mu_1, \mu_2, ..., \mu_k) &= C(\mu_1) + C(\mu_2) + ... + C(\mu_k) & \text{where} \\ C(\mu_j) &= \text{total squared distance of each data point } \vec{x}_i \\ & \text{in group } j \text{ to centroid } \mu_j \end{split}$$

Step 3: Keep the groups fixed, and update the centroids by moving each centroid to the center of its group (by averaging coordinates).

• Let's argue why this minimizes $C(\mu_i)$, for each group *j*.

Why does k-Means work? (Step 3)

 $C(\mu_j)$ = total squared distance of each data point \vec{x}_i in group *j* to centroid μ_j

Suppose group *j* contains the points (4, 3), (6, 4), and (8, 2). Where should we put $\mu_j = \begin{bmatrix} a \\ b \end{bmatrix}$ to minimize $C(\mu_j)$?



Cost and empirical risk

On the previous slide, we saw a function of the form

$$\begin{split} C(\mu_j) &= C(a,b) = (4-a)^2 + (3-b)^2 \\ &+ (6-a)^2 + (4-b)^2 \\ &+ (8-a)^2 + (2-b)^2 \end{split}$$

- C(a, b) can be thought of as the sum of two separate functions, f(a) and g(b).
 - ► $f(a) = (4 a)^2 + (6 a)^2 + (8 a)^2$ computes the total squared distance of each x_1 coordinate to a.
 - From earlier in the course, we know that $a^* = \frac{4+6+8}{3} = 6$ minimizes f(a).

Practical considerations

Initialization

- Depending on our initial centroids, k-Means may "converge" to a clustering that doesn't actually have the lowest possible inertia.
 - In other words, like gradient descent, k-Means can get caught in a local minimum.
- Some solutions:
 - Run k-Means several times, each with different randomly chosen initial centroids. Keep track of the inertia of the final result in each attempt. Choose the attempt with the lowest inertia.
 - k-Means++: choose one initial centroid at random, and choose the remaining initial centroids by maximizing distance from all other centroids.

Choosing k

- Note that as *k* increases, inertia decreases.
 - Intuitively, as we add more centroids, the distance between each point and its closest centroid will drop.
- But the goal of clustering is to put data points into groups, and having a large number of groups may not be meaningful.
- ▶ This suggests a tradeoff between *k* and inertia.

The "elbow" method

- Strategy: run k-Means Clustering for many choices of k (e.g. k = 1, 2, 3, ..., 8).
- Compute the value of inertia for each resulting set of centroids.
- Plot a graph of inertia vs k.
- Choose the value of k that appears at an "elbow".



See the notebook for a demo.

Low inertia isn't everything!

- Even if k-Means works as intended and finds the choice of centroids that minimize inertia, the resulting clustering may not look "right" to us humans.
 - Recall, inertia measures the total squared distance to centroids.
 - This metric doesn't always match our intuition.
- Let's look at some examples at https://tinyurl.com/40akmeans.
 - ► Go to "I'll Choose" and "Smiley Face". Good luck!



Other clustering techniques

- k-Means Clustering is just one way to cluster data.
- There are many others, each of which work differently and produce different kinds of results.
- Another common technique: **agglomerative clustering**.
 - High level: start out with each point being in its own cluster. Repeatedly combine clusters until only k are left.
- Check out this chart.

Next time

- ► Friday: Midterm
- Monday: Review for clustering & Introduction to Probability