Lecture 26 – Logistic Regression and Maximum Likelihood Estimation (continued)



DSC 40A, Fall 2022 @ UC San Diego

Dr. Truong Son Hy, with help from many others Some materials are taken from Prof. Greg Shakhnarovich's ML course at TTIC.

Announcements

- The final is coming!
- ▶ There will be a review session.

Agenda

- Logistic Regression.
- Maximum Likelihood Estimation.

Logistic Regression

Linear classifier

Hypothesis:

$$\hat{y} = h(\vec{x}) = \operatorname{sign}(\vec{x} \cdot \vec{w} + w_0)$$

- Classifying using a linear decision boundary effectively reduces the data dimension to 1.
- ▶ We need to find the direction w and location w₀ of the boundary.
- ▶ We want to minimize the expected **zero/one** loss for classifier $h : X \rightarrow Y$, which for (\vec{x}, y) is:

$$L(h(\vec{x}), y) = \begin{cases} 0 & \text{if } h(\vec{x}) = y, \\ 1 & \text{if } h(\vec{x}) \neq y. \end{cases}$$

Empirical Risk Minimization

- ► The risk (expected loss) of a C-way classifier $h(\vec{x})$: $R(h) = E_{p(\vec{x},y)}[L(h(\vec{x}), y)].$
- We can write the risk in intergral form:

$$R(h) = \int_{\vec{x}} \sum_{c=1}^{C} L(h(\vec{x}), c) p(\vec{x}, y = c) d\vec{x}$$
$$\Leftrightarrow R(h) = \int_{\vec{x}} \left[\sum_{c=1}^{C} L(h(\vec{x}), c) p(y = c | \vec{x}) \right] p(\vec{x}) d\vec{x}$$

Clearly, it is enough to minimize the conditional risk for any x:

$$R(h|\vec{x}) = \sum_{c=1}^{C} L(h(\vec{x}), c)p(y = c|\vec{x})$$

Conditional risk of a classifier

Conditional risk:

$$R(h|\vec{x}) = \sum_{c=1}^{C} L(h(\vec{x}), c) p(y = c | \vec{x})$$

We can factorize this risk as:

$$R(h|\vec{x}) = 0 \cdot p(y = h(\vec{x})|\vec{x}) + 1 \cdot \sum_{c \neq h(\vec{x})} p(y = c|\vec{x}),$$

$$\Leftrightarrow R(h) = \sum_{c \neq h(\vec{x})} p(y = c | \vec{x}) = 1 - p(y = h(\vec{x}) | \vec{x})$$

To minimize conditional risk given x, the classifier must decide:

$$h(\vec{x}) = \operatorname{argmax}_{c} p(y = c | \vec{x})$$

Log-odds ratio

• Optimal rule $h(\vec{x}) = \operatorname{argmax}_c p(y = c | \vec{x})$ is equivalent to:

$$h(\vec{x}) = c^* \Leftrightarrow \frac{p(y = c^* | \vec{x})}{p(y = c | \vec{x})} \ge 1 \quad \forall c$$

that is equivalent to:

$$\log \frac{p(y = c^* | \vec{x})}{p(y = c | \vec{x})} \ge 0 \quad \forall c$$

▶ For the binary case:

$$h(\vec{x}) = 1 \Leftrightarrow \log \frac{p(y = 1 | \vec{x})}{p(y = 0 | \vec{x})} \ge 0.$$

The logistic model

We can model the (unknown) decision boundary directly:

$$\log \frac{p(y=1|\vec{x})}{p(y=0|\vec{x})} = \vec{x} \cdot \vec{w} + w_0 = 0.$$

Since $p(y = 1 | \vec{x}) = 1 - p(y = 0 | \vec{x})$, we have (after exponentiating):

$$\frac{p(y=1|\vec{x})}{1-p(y=1|\vec{x})} = \exp(\vec{x}\cdot\vec{w}+w_0) = 1$$

The logistic model

We can model the (unknown) decision boundary directly:

$$\log \frac{p(y=1|\vec{x})}{p(y=0|\vec{x})} = \vec{x} \cdot \vec{w} + w_0 = 0.$$

Since $p(y = 1 | \vec{x}) = 1 - p(y = 0 | \vec{x})$, we have (after exponentiating):

$$\frac{p(y=1|\vec{x})}{1-p(y=1|\vec{x})} = \exp(\vec{x}\cdot\vec{w}+w_0) = 1$$
$$\Rightarrow \frac{1}{p(y=1|\vec{x})} = 1 + \exp(-\vec{x}\cdot\vec{w}-w_0) = 2$$

The logistic model

We can model the (unknown) decision boundary directly:

$$\log \frac{p(y=1|\vec{x})}{p(y=0|\vec{x})} = \vec{x} \cdot \vec{w} + w_0 = 0.$$

Since $p(y = 1 | \vec{x}) = 1 - p(y = 0 | \vec{x})$, we have (after exponentiating):

$$\frac{p(y=1|\vec{x})}{1-p(y=1|\vec{x})} = \exp(\vec{x}\cdot\vec{w}+w_0) = 1$$
$$\Rightarrow \frac{1}{p(y=1|\vec{x})} = 1 + \exp(-\vec{x}\cdot\vec{w}-w_0) = 2$$
$$\Rightarrow p(y=1|\vec{x}) = \frac{1}{1+\exp(-\vec{x}\cdot\vec{w}-w_0)} = \frac{1}{2}$$

The logistic function

► The logistic / sigmoid function: $\sigma(x) = \frac{1}{1+e^{-x}}$. For any $x \in R$: $0 \le \sigma(x) \le 1$. Monotonic: $\lim_{x\to-\infty} \sigma(x) = 0$ and $\lim_{x\to+\infty} \sigma(x) = 1$.



► We have:

$$p(y=1|\vec{x}) = \frac{1}{1 + \exp(-\vec{x} \cdot \vec{w} - w_0)} = \sigma(h(\vec{x}))$$

Logistic function in \mathbb{R}^d

For $\vec{x} \in \mathbb{R}^d$, $\sigma(\vec{w} \cdot \vec{x} + w_0)$ is a scalar function of a scalar variable $\vec{w} \cdot \vec{x} + w_0$.



► The direction of w determines the orientation, w₀ determines the location, and ||w || determines the slope.

Decision boundary of Logistic Regression

With linear logistic model, we get a linear decision boundary:

$$p(y = 1 | \vec{x}) = \sigma(\vec{w} \cdot \vec{x} + w_0) = \frac{1}{2} \Leftrightarrow \vec{w} \cdot \vec{x} + w_0 = 0$$



Maximum Likelihood Estimation

Likelihood under the logistic model

- Regression: observe values, measure residuals under the model.
- Logistic regression: observe labels, measure their probability under the model.

$$p(y_i | \vec{x}_i; \vec{w}) = \begin{cases} \sigma(\vec{w} \cdot \vec{x}_i + w_0) & \text{if } y_i = 1, \\ 1 - \sigma(\vec{w} \cdot \vec{x}_i + w_0) & \text{if } y_i = 0. \end{cases}$$

We can write it compactly as:

$$p(y_i | \vec{x}_i; \vec{w}, w_0) = \sigma(\vec{w} \cdot \vec{x}_i + w_0)^{y_i} \cdot (1 - \sigma(\vec{w} \cdot \vec{x}_i + w_0))^{1 - y_i}.$$

Likelihood under the logistic model

Suppose we are given a dataset $D = \{(\vec{x}_i, y_i)\}_{i=1}^N$ of N samples. The **likelihood** of \vec{w} and w_0 on this data is defined as:

$$p(Y|X; \vec{w}, w_0) = \prod_{i=1}^{N} p(y_i | \vec{x}_i; \vec{w}, w_0)$$

The log-likelihood is then:

 $\log p(Y|X;\vec{w},w_0) =$

Likelihood under the logistic model

Suppose we are given a dataset $D = \{(\vec{x}_i, y_i)\}_{i=1}^N$ of N samples. The **likelihood** of \vec{w} and w_0 on this data is defined as:

$$p(Y|X; \vec{w}, w_0) = \prod_{i=1}^{N} p(y_i | \vec{x}_i; \vec{w}, w_0)$$

The log-likelihood is then:

$$\log p(Y|X; \vec{w}, w_0) = \sum_{i=1}^N \log p(y_i | \vec{x}_i; \vec{w}, w_0),$$

that is equal to:

$$\log p(Y|X; \vec{w}, w_0) = \sum_{i=1}^N y_i \log \sigma(\vec{w} \cdot \vec{x}_i + w_0) + (1 - y_i) \log(1 - \sigma(\vec{w} \cdot \vec{x}_i + w_0))$$

Maximum Likelihood Solution

We want to find \vec{w} and w_0 that **maximizes** the log-likelihood:

$$\log p(Y|X; \vec{w}, w_0) = \sum_{i=1}^{N} y_i \log \sigma(\vec{w} \cdot \vec{x}_i + w_0) + (1 - y_i) \log(1 - \sigma(\vec{w} \cdot \vec{x}_i + w_0))$$

Maximum Likelihood Solution

We want to find \vec{w} and w_0 that **maximizes** the log-likelihood:

$$\log p(Y|X; \vec{w}, w_0) = \sum_{i=1}^{N} y_i \log \sigma(\vec{w} \cdot \vec{x}_i + w_0) + (1 - y_i) \log(1 - \sigma(\vec{w} \cdot \vec{x}_i + w_0))$$

We find the derivatives:

$$\frac{\partial}{\partial w_0} \log p(Y|X; \vec{w}, w_0) = \sum_{i=1}^{N} (y_i - \sigma(\vec{w} \cdot \vec{x}_i + w_0))$$
$$\frac{\partial}{\partial w_j} \log p(Y|X; \vec{w}, w_0) = \sum_{i=1}^{N} (y_i - \sigma(\vec{w} \cdot \vec{x}_i + w_0)) x_{ij}$$

We can treat $y_i - p(y_i | \vec{x}_i) = y_i - \sigma(\vec{w} \cdot \vec{x}_i + w_0)$ as the **prediction** error of the model on \vec{x}_i, y_i .

Derivatives for \ln and σ

Logarithm:

$$\frac{d}{dx}\ln(x) = \frac{1}{x}, \quad \frac{d}{dx}\log_a(x) = \frac{1}{x\ln(a)}$$

Derivatives for \ln and σ

Logarithm:

$$\frac{d}{dx}\ln(x) = \frac{1}{x}, \quad \frac{d}{dx}\log_a(x) = \frac{1}{x\ln(a)}$$

► Sigmoid: $\sigma(x) = \frac{1}{1 + e^{-x}}$ $\frac{d}{dx}\sigma(x) = \frac{d}{dx}\frac{1}{1 + e^{-x}} = \frac{d}{dx}(1 + e^{-x})^{-1} = -(1 + e^{-x})^{-2}\frac{d}{dx}(1 + e^{-x})$

Derivatives for \ln and σ

Logarithm:

$$\frac{d}{dx}\ln(x) = \frac{1}{x}, \quad \frac{d}{dx}\log_a(x) = \frac{1}{x\ln(a)}$$

Sigmoid: $\sigma(x) = \frac{1}{1 + e^{-x}}$ $\frac{d}{dx}\sigma(x) = \frac{d}{dx}\frac{1}{1+e^{-x}} = \frac{d}{dx}(1+e^{-x})^{-1} = -(1+e^{-x})^{-2}\frac{d}{dx}(1+e^{-x})$ $\Leftrightarrow \frac{d}{dx}\sigma(x) = (1 + e^{-x})^{-2}e^{-x} = \frac{e^{-x}}{(1 + e^{-x})^2} = \frac{1}{1 + e^{-x}} \cdot \frac{e^{-x}}{1 + e^{-x}}$ $\Leftrightarrow \frac{d}{dx}\sigma(x) = \sigma(x) \cdot \frac{e^{-x} + 1 - 1}{1 + e^{-x}} = \sigma(x) \cdot [1 - \sigma(x)]$

Partial derivatives for $\log \sigma(\vec{w} \cdot \vec{x}_i + w_0)$

For w_0 :

$$\frac{\partial}{\partial w_0} \log \sigma(\vec{w} \cdot \vec{x}_i + w_0) = \frac{1}{\sigma(\vec{w} \cdot \vec{x}_i + w_0)} \frac{\partial}{\partial w_0} \sigma(\vec{w} \cdot \vec{x}_i + w_0)$$

Partial derivatives for $\log \sigma(\vec{w} \cdot \vec{x}_i + w_0)$

For w_0 :

$$\frac{\partial}{\partial w_0} \log \sigma(\vec{w} \cdot \vec{x}_i + w_0) = \frac{1}{\sigma(\vec{w} \cdot \vec{x}_i + w_0)} \frac{\partial}{\partial w_0} \sigma(\vec{w} \cdot \vec{x}_i + w_0)$$
$$= \frac{1}{\sigma(\vec{w} \cdot \vec{x}_i + w_0)} \sigma(\vec{w} \cdot \vec{x}_i + w_0) [1 - \sigma(\vec{w} \cdot \vec{x}_i + w_0)] \frac{\partial}{\partial w_0} (\vec{w} \cdot \vec{x}_i + w_0)$$

Partial derivatives for $\log \sigma(\vec{w} \cdot \vec{x}_i + w_0)$

For w_0 :

$$\frac{\partial}{\partial w_0} \log \sigma(\vec{w} \cdot \vec{x}_i + w_0) = \frac{1}{\sigma(\vec{w} \cdot \vec{x}_i + w_0)} \frac{\partial}{\partial w_0} \sigma(\vec{w} \cdot \vec{x}_i + w_0)$$
$$= \frac{1}{\sigma(\vec{w} \cdot \vec{x}_i + w_0)} \sigma(\vec{w} \cdot \vec{x}_i + w_0) [1 - \sigma(\vec{w} \cdot \vec{x}_i + w_0)] \frac{\partial}{\partial w_0} (\vec{w} \cdot \vec{x}_i + w_0)$$
$$= 1 - \sigma(\vec{w} \cdot \vec{x}_i + w_0)$$

For w_i :

$$\frac{\partial}{\partial w_j} \log \sigma(\vec{w} \cdot \vec{x}_i + w_0) = \frac{1}{\sigma(\vec{w} \cdot \vec{x}_i + w_0)} \frac{\partial}{\partial w_j} \sigma(\vec{w} \cdot \vec{x}_i + w_0)$$
$$= \frac{1}{\sigma(\vec{w} \cdot \vec{x}_i + w_0)} \sigma(\vec{w} \cdot \vec{x}_i + w_0) [1 - \sigma(\vec{w} \cdot \vec{x}_i + w_0)] \frac{\partial}{\partial w_j} (\vec{w} \cdot \vec{x}_i + w_0)$$
$$= [1 - \sigma(\vec{w} \cdot \vec{x}_i + w_0)] x_{ij}$$

Partial derivatives for $\log[1 - \sigma(\vec{w} \cdot \vec{x}_i + w_0)]$ For w_0 :

$$\frac{\partial}{\partial w_0} \log[1 - \sigma(\vec{w} \cdot \vec{x}_i + w_0)] = \frac{1}{1 - \sigma(\vec{w} \cdot \vec{x}_i + w_0)} \frac{\partial}{\partial w_0} [1 - \sigma(\vec{w} \cdot \vec{x}_i + w_0)]$$
$$= \frac{-1}{1 - \sigma(\vec{w} \cdot \vec{x}_i + w_0)} \sigma(\vec{w} \cdot \vec{x}_i + w_0) [1 - \sigma(\vec{w} \cdot \vec{x}_i + w_0)] \frac{\partial}{\partial w_0} (\vec{w} \cdot \vec{x}_i + w_0)$$
$$= -\sigma(\vec{w} \cdot \vec{x}_i + w_0)$$

Partial derivatives for $\log[1 - \sigma(\vec{w} \cdot \vec{x}_i + w_0)]$ For w_0 :

$$\frac{\partial}{\partial w_0} \log[1 - \sigma(\vec{w} \cdot \vec{x}_i + w_0)] = \frac{1}{1 - \sigma(\vec{w} \cdot \vec{x}_i + w_0)} \frac{\partial}{\partial w_0} [1 - \sigma(\vec{w} \cdot \vec{x}_i + w_0)]$$
$$= \frac{-1}{1 - \sigma(\vec{w} \cdot \vec{x}_i + w_0)} \sigma(\vec{w} \cdot \vec{x}_i + w_0) [1 - \sigma(\vec{w} \cdot \vec{x}_i + w_0)] \frac{\partial}{\partial w_0} (\vec{w} \cdot \vec{x}_i + w_0)$$
$$= -\sigma(\vec{w} \cdot \vec{x}_i + w_0)$$

For w_i:

$$\frac{\partial}{\partial w_j} \log[1 - \sigma(\vec{w} \cdot \vec{x}_i + w_0)] = \frac{1}{1 - \sigma(\vec{w} \cdot \vec{x}_i + w_0)} \frac{\partial}{\partial w_j} [1 - \sigma(\vec{w} \cdot \vec{x}_i + w_0)]$$

$$= \frac{-1}{1 - \sigma(\vec{w} \cdot \vec{x}_{i} + w_{0})} \sigma(\vec{w} \cdot \vec{x}_{i} + w_{0}) [1 - \sigma(\vec{w} \cdot \vec{x}_{i} + w_{0})] \frac{\sigma}{\partial w_{j}} (\vec{w} \cdot \vec{x}_{i} + w_{0})$$
$$= -\sigma(\vec{w} \cdot \vec{x}_{i} + w_{0}) x_{ij}$$

Partial derivatives for $\log p(Y|X; \vec{w}, w_0)$

Log-likelihood:

$$\log p(Y|X; \vec{w}, w_0) = \sum_{i=1}^{N} y_i \log \sigma(\vec{w} \cdot \vec{x}_i + w_0) + (1 - y_i) \log(1 - \sigma(\vec{w} \cdot \vec{x}_i + w_0))$$

For w_0 :

$$\frac{\partial}{\partial w_0} \log p(Y|X; \vec{w}, w_0) = \sum_{i=1}^N y_i [1 - \sigma(\vec{w} \cdot \vec{x}_i + w_0)] + (1 - y_i) [-\sigma(\vec{w} \cdot \vec{x}_i + w_0)]$$

$$=\sum_{i=1}^N y_i - y_i \sigma(\vec{w}\cdot\vec{x}_i+w_0) - \sigma(\vec{w}\cdot\vec{x}_i+w_0) + y_i \sigma(\vec{w}\cdot\vec{x}_i+w_0)$$

$$= \sum_{i=1}^{N} [y_i - \sigma(\vec{w} \cdot \vec{x}_i + w_0)]$$

Partial derivatives for $\log p(Y|X; \vec{w}, w_0)$

Log-likelihood:

$$\log p(Y|X; \vec{w}, w_0) = \sum_{i=1}^{N} y_i \log \sigma(\vec{w} \cdot \vec{x}_i + w_0) + (1 - y_i) \log(1 - \sigma(\vec{w} \cdot \vec{x}_i + w_0))$$

For w_i:

$$\frac{\partial}{\partial w_j} \log p(\boldsymbol{Y} | \boldsymbol{X}; \vec{w}, w_0) = \sum_{i=1}^N y_i [1 - \sigma(\vec{w} \cdot \vec{x}_i + w_0)] \boldsymbol{x}_{ij} + (1 - y_i) [-\sigma(\vec{w} \cdot \vec{x}_i + w_0)] \boldsymbol{x}_{ij}$$

$$= \sum_{i=1}^{N} [y_i - y_i \sigma(\vec{w} \cdot \vec{x}_i + w_0) - \sigma(\vec{w} \cdot \vec{x}_i + w_0) + y_i \sigma(\vec{w} \cdot \vec{x}_i + w_0)] x_{ij}$$

$$= \sum_{i=1}^{N} [y_i - \sigma(\vec{w} \cdot \vec{x}_i + w_0)] x_{ij}$$

Gradient ascent for MLE

Thus, we get the gradients as follows:

$$\frac{\partial}{\partial w_0} \log p(Y|X; \vec{w}) = \sum_{i=1}^{N} (y_i - \sigma(\vec{w} \cdot \vec{x}_i + w_0))$$
$$\frac{\partial}{\partial w_j} \log p(Y|X; \vec{w}) = \sum_{i=1}^{N} (y_i - \sigma(\vec{w} \cdot \vec{x}_i + w_0)) x_{ij}$$

We can cycle through the examples, accumulating the gradient, and then applying the accumulated value to form an update:

$$\begin{split} & w_0^{(t+1)} \leftarrow w_0^{(t)} + \alpha \cdot \frac{\partial}{\partial w_0} \log p(Y|X; \vec{w}, w_0) \\ & \vec{w}^{(t+1)} \leftarrow \vec{w}^{(t)} + \alpha \cdot \frac{\partial}{\partial \vec{w}} \log p(Y|X; \vec{w}, w_0) \vec{x} \end{split}$$

where α is the learning rate.

Gradient ascent for MLE

- Recall that we really want to minimize the 0/1 loss.
- Instead, we are minimizing the log-loss or maximizing the log-likelihood:

$$\operatorname{argmax}_{\vec{w}} \sum_{i=1}^{N} \log p(y_i | \vec{x}_i; \vec{w}) = \operatorname{argmin}_{\vec{w}} - \sum_{i=1}^{N} \log p(y_i | \vec{x}_i; \vec{w})$$

This is a surrogate loss: we work with it since it is not computationally feasible to optimize the 0/1 loss directly.

Problem of gradient descent and gradient ascent

We need to choose the learning rate α rather carefully:

- ▶ Too small \Rightarrow Slow convergence.
- Too large \Rightarrow Overshoot and oscillation.



Newton-Raphson algorithm

The Newton-Raphson algorithm: approximate the local shape of the loss function L as a quadratic function:

$$\vec{w}_{\text{new}} \leftarrow \vec{w} - H^{-1} \frac{\partial}{\partial \vec{w}} L(\vec{w}),$$

where H is the Hessian matrix of second derivatives:

$$H = \begin{pmatrix} \frac{\partial^2 L}{\partial w_0^2} & \frac{\partial^2 L}{\partial w_0 \partial w_1} & \cdots & \frac{\partial^2 L}{\partial w_0 \partial w_d} \\ \frac{\partial^2 L}{\partial w_0 \partial w_1} & \frac{\partial^2 L}{\partial w_1^2} & \cdots & \frac{\partial^2 L}{\partial w_1 \partial w_d} \\ \cdots & \cdots & \cdots & \cdots \\ \frac{\partial^2 L}{\partial w_d \partial w_0} & \frac{\partial^2 L}{\partial w_d \partial w_1} & \cdots & \frac{\partial^2 L}{\partial w_d^2} \end{pmatrix}$$

This is a second-order method, while gradient descent/ascent are first-order methods.

Generalized additive models

As with regression, we can extend the MLE framework for logistic regression to arbitrary features (basis functions):

$$p(y=1|\vec{x})=\sigma(w_0+\phi_1(\vec{x})+\cdots+\phi_m(\vec{x})).$$

Example: Quadratic logistic regression in 2D

$$p(y=1|\vec{x})=\sigma(w_0+w_1x_1+w_2x_2+w_3x_1^2+w_4x_2^2),$$

with quadratic decision boundary

$$W_0 + W_1 X_1 + W_2 X_2 + W_3 X_1^2 + W_4 X_2^2 = 0.$$

Generalized additive models



Quadratic



We can also include x_1x_2 :



Library for Logistic Regression

Examples

>>> from sklearn.datasets import load_iris
>>> from sklearn.linear_model import logisticRegression
>>> x, y = load_iris(return_X_y=True)
>>> clf = LogisticRegression(random_state=0).fit(X, y)
>>> clf.predict(X[:2, :])
array([0, 0])
>>> clf.predict_proba(X[:2, :])
array([[9.8...e-01, 1.8...e-02, 1.4...e-08],
 [9.7...e-01, 2.8...e-02, ...e-08]])
>>> clf.score(X, y)
0.97...

https://scikit-learn.org/stable/modules/generated/ sklearn.linear_model.LogisticRegression.html



The course summary and practical questions for the final exam!