Lecture 26 - Logistic Regression and Maximum Likelihood Estimation (continued)


DSC 40A, Fall 2022 @ UC San Diego
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Some materials are taken from Prof. Greg Shakhnarovich's ML course at TTIC.

## Announcements

The final is coming!

There will be a review session.

## Agenda

- Logistic Regression.
- Maximum Likelihood Estimation.

Logistic Regression

## Linear classifier

- Hypothesis:

$$
\hat{y}=h(\vec{x})=\operatorname{sign}\left(\vec{x} \cdot \vec{w}+w_{0}\right)
$$

- Classifying using a linear decision boundary effectively reduces the data dimension to 1.
- We need to find the direction $\vec{w}$ and location $w_{0}$ of the boundary.
- We want to minimize the expected zero/one loss for classifier $h: X \rightarrow Y$, which for $(\vec{x}, y)$ is:

$$
L(h(\vec{x}), y)= \begin{cases}0 & \text { if } h(\vec{x})=y \\ 1 & \text { if } h(\vec{x}) \neq y\end{cases}
$$

## Empirical Risk Minimization

- The risk (expected loss) of a C-way classifier $h(\vec{x})$ :

$$
R(h)=E_{p(\vec{x}, y)}[L(h(\vec{x}), y)] .
$$

- We can write the risk in intergral form:

$$
\begin{aligned}
& R(h)=\int_{\vec{x}} \sum_{c=1}^{c} L(h(\vec{x}), c) p(\vec{x}, y=c) d \vec{x} \\
\Leftrightarrow & R(h)=\int_{\vec{x}}\left[\sum_{c=1}^{c} L(h(\vec{x}), c) p(y=c \mid \vec{x})\right] p(\vec{x}) d \vec{x}
\end{aligned}
$$

- Clearly, it is enough to minimize the conditional risk for any $\vec{x}$ :

$$
R(h \mid \vec{x})=\sum_{c=1}^{c} L(h(\vec{x}), c) p(y=c \mid \vec{x})
$$

## Conditional risk of a classifier

- Conditional risk:

$$
R(h \mid \vec{x})=\sum_{c=1}^{c} L(h(\vec{x}), c) p(y=c \mid \vec{x})
$$

- We can factorize this risk as:

$$
\begin{aligned}
& R(h \mid \vec{x})=0 \cdot p(y=h(\vec{x}) \mid \vec{x})+1 \cdot \sum_{c \neq h(\vec{x})} p(y=c \mid \vec{x}), \\
& \Leftrightarrow R(h)=\sum_{c \neq h(\vec{x})} p(y=c \mid \vec{x})=1-p(y=h(\vec{x}) \mid \vec{x})
\end{aligned}
$$

- To minimize conditional risk given $\vec{x}$, the classifier must decide:

$$
h(\vec{x})=\operatorname{argmax}_{c} p(y=c \mid \vec{x})
$$

## Log-odds ratio

- Optimal rule $h(\vec{x})=\operatorname{argmax}_{c} p(y=c \mid \vec{x})$ is equivalent to:

$$
h(\vec{x})=c^{*} \Leftrightarrow \frac{p\left(y=c^{*} \mid \vec{x}\right)}{p(y=c \mid \vec{x})} \geq 1 \quad \forall c
$$

that is equivalent to:

$$
\log \frac{p\left(y=c^{*} \mid \vec{x}\right)}{p(y=c \mid \vec{x})} \geq 0 \quad \forall c
$$

- For the binary case:

$$
h(\vec{x})=1 \Leftrightarrow \log \frac{p(y=1 \mid \vec{x})}{p(y=0 \mid \vec{x})} \geq 0 .
$$

## The logistic model

- We can model the (unknown) decision boundary directly:

$$
\log \frac{p(y=1 \mid \vec{x})}{p(y=0 \mid \vec{x})}=\vec{x} \cdot \vec{w}+w_{0}=0
$$

- Since $p(y=1 \mid \vec{x})=1-p(y=0 \mid \vec{x})$, we have (after exponentiating):

$$
\frac{p(y=1 \mid \vec{x})}{1-p(y=1 \mid \vec{x})}=\exp \left(\vec{x} \cdot \vec{w}+w_{0}\right)=1
$$

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& \frac{p(y=1 \mid \vec{x})}{1-p(y=1 \mid \vec{x})}=\exp \left(\vec{x} \cdot \vec{w}+w_{0}\right)=1 \\
\Rightarrow & \frac{1}{p(y=1 \mid \vec{x})}=1+\exp \left(-\vec{x} \cdot \vec{w}-w_{0}\right)=2
\end{aligned}
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\Rightarrow & p(y=1 \mid \vec{x})=\frac{1}{1+\exp \left(-\vec{x} \cdot \vec{w}-w_{0}\right)}=\frac{1}{2}
\end{aligned}
$$

## The logistic function

$\Rightarrow$ The logistic / sigmoid function: $\sigma(x)=\frac{1}{1+e^{-x}}$.
For any $x \in R: 0 \leq \sigma(x) \leq 1$.
Monotonic: $\lim _{x \rightarrow-\infty} \sigma(x)=0$ and $\lim _{x \rightarrow+\infty} \sigma(x)=1$.


- We have:

$$
p(y=1 \mid \vec{x})=\frac{1}{1+\exp \left(-\vec{x} \cdot \vec{w}-w_{0}\right)}=\sigma(h(\vec{x}))
$$

## Logistic function in $\mathbb{R}^{d}$

$\Rightarrow$ For $\vec{x} \in \mathbb{R}^{d}, \sigma\left(\vec{w} \cdot \vec{x}+w_{0}\right)$ is a scalar function of a scalar variable $\vec{w} \cdot \vec{x}+w_{0}$.

$>$ The direction of $\vec{w}$ determines the orientation, $w_{0}$ determines the location, and $\|\vec{w}\|$ determines the slope.

## Decision boundary of Logistic Regression

With linear logistic model, we get a linear decision boundary:

$$
p(y=1 \mid \vec{x})=\sigma\left(\vec{w} \cdot \vec{x}+w_{0}\right)=\frac{1}{2} \Leftrightarrow \vec{w} \cdot \vec{x}+w_{0}=0
$$



## Maximum Likelihood Estimation

## Likelihood under the logistic model

- Regression: observe values, measure residuals under the model.
- Logistic regression: observe labels, measure their probability under the model.

$$
p\left(y_{i} \mid \vec{x}_{i} ; \vec{w}\right)= \begin{cases}\sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right) & \text { if } y_{i}=1 \\ 1-\sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right) & \text { if } y_{i}=0 .\end{cases}
$$

We can write it compactly as:

$$
p\left(y_{i} \mid \vec{x}_{i} ; \vec{w}, w_{0}\right)=\sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)^{y_{i}} \cdot\left(1-\sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)\right)^{1-y_{i}} .
$$

## Likelihood under the logistic model

Suppose we are given a dataset $D=\left\{\left(\vec{x}_{i}, y_{i}\right)\right\}_{i=1}^{N}$ of $N$ samples. The likelihood of $\vec{w}$ and $w_{0}$ on this data is defined as:

$$
p\left(Y \mid X ; \vec{w}, w_{0}\right)=\prod_{i=1}^{N} p\left(y_{i} \mid \vec{x}_{i} ; \vec{w}, w_{0}\right)
$$

The log-likelihood is then:

$$
\log p\left(Y \mid X ; \vec{w}, w_{0}\right)=
$$

## Likelihood under the logistic model

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$$

The log-likelihood is then:

$$
\log p\left(Y \mid X ; \vec{w}, w_{0}\right)=\sum_{i=1}^{N} \log p\left(y_{i} \mid \vec{x}_{i} ; \vec{w}, w_{0}\right),
$$

that is equal to:
$\log p\left(Y \mid X ; \vec{w}, w_{0}\right)=\sum_{i=1}^{N} y_{i} \log \sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)+\left(1-y_{i}\right) \log \left(1-\sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)\right)$

## Maximum Likelihood Solution

We want to find $\vec{w}$ and $w_{0}$ that maximizes the log-likelihood:
$\log p\left(Y \mid X ; \vec{w}, w_{0}\right)=\sum_{i=1}^{N} y_{i} \log \sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)+\left(1-y_{i}\right) \log \left(1-\sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)\right)$

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We find the derivatives:

$$
\begin{aligned}
& \frac{\partial}{\partial w_{0}} \log p\left(Y \mid X ; \vec{w}, w_{0}\right)=\sum_{i=1}^{N}\left(y_{i}-\sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)\right) \\
& \frac{\partial}{\partial w_{j}} \log p\left(Y \mid X ; \vec{w}, w_{0}\right)=\sum_{i=1}^{N}\left(y_{i}-\sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)\right) x_{i j}
\end{aligned}
$$

We can treat $y_{i}-p\left(y_{i} \mid \vec{x}_{i}\right)=y_{i}-\sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)$ as the prediction error of the model on $\vec{x}_{i}, y_{i}$.

## Derivatives for $\ln$ and $\sigma$

Logarithm:

$$
\frac{d}{d x} \ln (x)=\frac{1}{x}, \quad \frac{d}{d x} \log _{a}(x)=\frac{1}{x \ln (a)}
$$

## Derivatives for $\ln$ and $\sigma$

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$$

Sigmoid:

$$
\begin{gathered}
\sigma(x)=\frac{1}{1+e^{-x}} \\
\frac{d}{d x} \sigma(x)=\frac{d}{d x} \frac{1}{1+e^{-x}}=\frac{d}{d x}\left(1+e^{-x}\right)^{-1}=-\left(1+e^{-x}\right)^{-2} \frac{d}{d x}\left(1+e^{-x}\right)
\end{gathered}
$$

## Derivatives for $\ln$ and $\sigma$

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\Leftrightarrow \frac{d}{d x} \sigma(x)=\left(1+e^{-x}\right)^{-2} e^{-x}=\frac{e^{-x}}{\left(1+e^{-x}\right)^{2}}=\frac{1}{1+e^{-x}} \cdot \frac{e^{-x}}{1+e^{-x}} \\
\Leftrightarrow \frac{d}{d x} \sigma(x)=\sigma(x) \cdot \frac{e^{-x}+1-1}{1+e^{-x}}=\sigma(x) \cdot[1-\sigma(x)]
\end{gathered}
$$

## Partial derivatives for $\log \sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)$

For $w_{0}$ :

$$
\frac{\partial}{\partial w_{0}} \log \sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)=\frac{1}{\sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)} \frac{\partial}{\partial w_{0}} \sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)
$$

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= & \frac{1}{\sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)} \sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)\left[1-\sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)\right] \frac{\partial}{\partial w_{0}}\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)
\end{aligned}
$$

Partial derivatives for $\log \sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)$
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=\frac{1}{\sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)} \sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)\left[1-\sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)\right] \frac{\partial}{\partial w_{0}}\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right) \\
=1-\sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)
\end{gathered}
$$

For $w_{j}$ :

$$
\begin{gathered}
\frac{\partial}{\partial w_{j}} \log \sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)=\frac{1}{\sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)} \frac{\partial}{\partial w_{j}} \sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right) \\
=\frac{1}{\sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)} \sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)\left[1-\sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)\right] \frac{\partial}{\partial w_{j}}\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right) \\
=\left[1-\sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)\right] x_{i j}
\end{gathered}
$$

Partial derivatives for $\log \left[1-\sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)\right]$
For $w_{0}$ :

$$
\begin{gathered}
\frac{\partial}{\partial w_{0}} \log \left[1-\sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)\right]=\frac{1}{1-\sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)} \frac{\partial}{\partial w_{0}}\left[1-\sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)\right] \\
=\frac{-1}{1-\sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)} \sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)\left[1-\sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)\right] \frac{\partial}{\partial w_{0}}\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right) \\
=-\sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)
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=-\sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)
\end{gathered}
$$

For $w_{j}$ :

$$
\begin{gathered}
\frac{\partial}{\partial w_{j}} \log \left[1-\sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)\right]=\frac{1}{1-\sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)} \frac{\partial}{\partial w_{j}}\left[1-\sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)\right] \\
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=-\sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right) x_{i j}
\end{gathered}
$$

## Partial derivatives for $\log p\left(Y \mid X ; \vec{w}, w_{0}\right)$

Log-likelihood:
$\log p\left(Y \mid X ; \vec{w}, w_{0}\right)=\sum_{i=1}^{N} y_{i} \log \sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)+\left(1-y_{i}\right) \log \left(1-\sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)\right)$
For $w_{0}$ :

$$
\begin{gathered}
\frac{\partial}{\partial w_{0}} \log p\left(Y \mid X ; \vec{w}, w_{0}\right)=\sum_{i=1}^{N} y_{i}\left[1-\sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)\right]+\left(1-y_{i}\right)\left[-\sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)\right] \\
=\sum_{i=1}^{N} y_{i}-y_{i} \sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)-\sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)+y_{i} \sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right) \\
=\sum_{i=1}^{N}\left[y_{i}-\sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)\right]
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## Log-likelihood:

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## For $w_{j}$ :

$$
\begin{gathered}
\frac{\partial}{\partial w_{j}} \log p\left(Y \mid X ; \vec{w}, w_{0}\right)=\sum_{i=1}^{N} y_{i}\left[1-\sigma\left(\vec{w}^{N} \cdot \vec{x}_{i}+w_{0}\right)\right] x_{i j}+\left(1-y_{i}\right)\left[-\sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)\right] x_{i j} \\
=\sum_{i=1}^{N}\left[y_{i}-y_{i} \sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)-\sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)+y_{i} \sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)\right] x_{i j} \\
=\sum_{i=1}^{N}\left[y_{i}-\sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)\right] x_{i j}
\end{gathered}
$$

## Gradient ascent for MLE

Thus, we get the gradients as follows:

$$
\begin{aligned}
& \frac{\partial}{\partial w_{0}} \log p(Y \mid X ; \vec{w})=\sum_{i=1}^{N}\left(y_{i}-\sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)\right) \\
& \frac{\partial}{\partial w_{j}} \log p(Y \mid X ; \vec{w})=\sum_{i=1}^{N}\left(y_{i}-\sigma\left(\vec{w} \cdot \vec{x}_{i}+w_{0}\right)\right) x_{i j}
\end{aligned}
$$

We can cycle through the examples, accumulating the gradient, and then applying the accumulated value to form an update:

$$
\begin{aligned}
& w_{0}^{(t+1)} \leftarrow w_{0}^{(t)}+\alpha \cdot \frac{\partial}{\partial w_{0}} \log p\left(Y \mid X ; \vec{w}, w_{0}\right) \\
& \vec{w}^{(t+1)} \leftarrow \vec{w}^{(t)}+\alpha \cdot \frac{\partial}{\partial \vec{w}} \log p\left(Y \mid X ; \vec{w}, w_{0}\right) \vec{X}
\end{aligned}
$$

where $\alpha$ is the learning rate.

## Gradient ascent for MLE

- Recall that we really want to minimize the $0 / 1$ loss.
- Instead, we are minimizing the log-loss or maximizing the log-likelihood:

$$
\operatorname{argmax}_{\vec{w}} \sum_{i=1}^{N} \log p\left(y_{i} \mid \vec{x}_{i} ; \vec{w}\right)=\operatorname{argmin}_{\vec{w}}-\sum_{i=1}^{N} \log p\left(y_{i} \mid \vec{x}_{i} ; \vec{w}\right)
$$

- This is a surrogate loss: we work with it since it is not computationally feasible to optimize the 0/1 loss directly.


## Problem of gradient descent and gradient ascent

We need to choose the learning rate $\alpha$ rather carefully:

- Too small $\Rightarrow$ Slow convergence.
- Too large $\Rightarrow$ Overshoot and oscillation.



## Newton-Raphson algorithm

- The Newton-Raphson algorithm: approximate the local shape of the loss function $L$ as a quadratic function:

$$
\vec{w}_{\text {new }} \leftarrow \vec{w}-H^{-1} \frac{\partial}{\partial \vec{w}} L(\vec{w})
$$

where $H$ is the Hessian matrix of second derivatives:

$$
H=\left(\begin{array}{cccc}
\frac{\partial^{2} L}{\partial w_{0}^{2}} & \frac{\partial^{2} L}{\partial w_{0} \partial w_{1}} & \cdots & \frac{\partial^{2} L}{\partial w_{0} \partial w_{d}} \\
\frac{\partial^{2} L}{\partial w_{0} \partial w_{1}} & \frac{\partial^{2} L}{\partial w_{1}^{2}} & \cdots & \frac{\partial^{2} L}{\partial w_{1} \partial w_{d}} \\
\cdots & \cdots & \cdots & \cdots \\
\frac{\partial^{2} L}{\partial w_{d} \partial w_{0}} & \frac{\partial^{2} L}{\partial w_{d} \partial w_{1}} & \cdots & \frac{\partial^{2} L}{\partial w_{d}^{2}}
\end{array}\right)
$$

- This is a second-order method, while gradient descent/ascent are first-order methods.


## Generalized additive models

- As with regression, we can extend the MLE framework for logistic regression to arbitrary features (basis functions):

$$
p(y=1 \mid \vec{x})=\sigma\left(w_{0}+\phi_{1}(\vec{x})+\cdots+\phi_{m}(\vec{x})\right) .
$$

- Example: Quadratic logistic regression in 2D

$$
p(y=1 \mid \vec{x})=\sigma\left(w_{0}+w_{1} x_{1}+w_{2} x_{2}+w_{3} x_{1}^{2}+w_{4} x_{2}^{2}\right)
$$

with quadratic decision boundary

$$
w_{0}+w_{1} x_{1}+w_{2} x_{2}+w_{3} x_{1}^{2}+w_{4} x_{2}^{2}=0
$$

## Generalized additive models

Linear


We can also include $x_{1} x_{2}$ :

Quadratic



## Library for Logistic Regression

Examples

```
>>> from sklearn.datasets import load_iris
>> from sklearn. linear_model import LogisticRegression
>> X, y = load_iris(return_X_y=True)
>> clf = LogisticRegression(random_state=0).fit(X, y)
>> clf.predict(X[:2, :])
array([0, 0])
>> clf.predict_proba(X[:2, :])
array([[9.8\ldotse-01, 1.8\ldotse-02, 1.4...e-08],
    [9.7...e-01, 2.8...e-02, ...e-08]])
>> clf.score(X, y)
0.97...
```

https://scikit-learn.org/stable/modules/generated/ sklearn.linear_model.LogisticRegression.html

## Next time

The course summary and practical questions for the final exam!

