# Module 12 – Multiple Linear Regression and Feature Engineering



#### **DSC 40A, Summer 2023**

#### Agenda

- Incorporating multiple features.
- Interpreting parameters.
- ► Feature engineering.

# Incorporating multiple features

#### Last time

We minimized the mean squared error for the prediction rule  $H(x) = w_0 + w_1 x$ , which was

$$R_{sq}(\vec{w}) = \frac{1}{n} ||\vec{y} - X\vec{w}||^2$$

We found that the minimizing  $\vec{w}$  satisfies the normal equations,  $X^T X \vec{w} = X^T \vec{y}$ .

• If  $X^T X$  is invertible, the solution is:

$$\vec{w}^* = (X^T X)^{-1} X^T \vec{y}$$

These same normal equations can be used to solve the multiple linear regression problem, where we use multiple features to predict an outcome. We simply need to adjust the design matrix X.

#### Multiple linear regression example

- We're want to fit a linear prediction rule with two features:
  H(experience, GPA) = w<sub>0</sub> + w<sub>1</sub>(experience) + w<sub>2</sub>(GPA)
- Collect data for each of n people:

Person #	Experience	GPA	Salary
1	3	3.7	85,000
2	6	3.3	95,000 105,000
3	10	3.1	105,000

We represent each person with a feature vector:

$$\vec{x}_1 = \begin{bmatrix} 3 \\ 3.7 \end{bmatrix}, \quad \vec{x}_2 = \begin{bmatrix} 6 \\ 3.3 \end{bmatrix}, \quad \vec{x}_3 = \begin{bmatrix} 10 \\ 3.1 \end{bmatrix}$$

### Prediction rule form determines design matrix

When our prediction rule is

 $H(experience, GPA) = w_0 + w_1(experience) + w_2(GPA),$ 

the hypothesis vector  $\vec{h} \in \mathbb{R}^n$  can be written

$$\vec{h} = \begin{bmatrix} H(\text{experience}_1, \text{GPA}_1) \\ H(\text{experience}_2, \text{GPA}_2) \\ \dots \\ H(\text{experience}_n, \text{GPA}_n) \end{bmatrix} = \begin{bmatrix} 1 & \text{experience}_1 & \text{GPA}_1 \\ 1 & \text{experience}_2 & \text{GPA}_2 \\ \dots & \dots & \dots \\ 1 & \text{experience}_n & \text{GPA}_n \end{bmatrix} \begin{bmatrix} w_0 \\ w_1 \\ w_2 \end{bmatrix}$$

 Notice that the rows of the design matrix are the (transposed) feature vectors, with an additional 1 in front.

# Notation for multiple linear regression

- We will need to keep track of multiple<sup>1</sup> features for every individual in our data set.
- As before, subscripts distinguish between individuals in our data set. We have *n* individuals (or training examples).
- Superscripts distinguish between features.<sup>2</sup> We have d features.
  - experience =  $x^{(1)}$
  - ► GPA =  $x^{(2)}$

<sup>&</sup>lt;sup>1</sup>In practice, we might use hundreds or even thousands of features. <sup>2</sup>Think of them as new variable names, such as new letters.

#### **Augmented feature vectors**

The augmented feature vector Aug(x) is the vector obtained by adding a 1 to the front of feature vector x:

$$\vec{x} = \begin{bmatrix} x^{(1)} \\ x^{(2)} \\ \vdots \\ x^{(d)} \end{bmatrix} \qquad \text{Aug}(\vec{x}) = \begin{bmatrix} 1 \\ x^{(1)} \\ x^{(2)} \\ \vdots \\ x^{(d)} \end{bmatrix} \qquad \vec{w} = \begin{bmatrix} w_0 \\ w_1 \\ w_2 \\ \vdots \\ w_d \end{bmatrix}$$

Then, our prediction rule is

$$H(\vec{x}) = w_0 + w_1 x^{(1)} + w_2 x^{(2)} + \dots + w_d x^{(d)}$$
  
=  $\vec{w} \cdot \text{Aug}(\vec{x})$ 

#### The general problem

We have *n* data points (or training examples):  $(\vec{x}_1, y_1), ..., (\vec{x}_n, y_n)$  where each  $\vec{x}_i$  is a feature vector of *d* features:

$$\vec{x}_{i} = \begin{bmatrix} x_{i}^{(1)} \\ x_{i}^{(2)} \\ \vdots \\ \vdots \\ x_{i}^{(d)} \end{bmatrix}$$

▶ We want to find a good linear prediction rule:

$$H(\vec{x}) = w_0 + w_1 x^{(1)} + w_2 x^{(2)} + \dots + w_d x^{(d)}$$
  
=  $\vec{w} \cdot \text{Aug}(\vec{x})$ 

### The general solution

Use design matrix

$$X = \begin{bmatrix} 1 & x_1^{(1)} & x_1^{(2)} & \dots & x_1^{(d)} \\ 1 & x_2^{(1)} & x_2^{(2)} & \dots & x_2^{(d)} \\ \dots & \dots & \dots & \dots & \dots \\ 1 & x_n^{(1)} & x_n^{(2)} & \dots & x_n^{(d)} \end{bmatrix} = \begin{bmatrix} \operatorname{Aug}(\vec{x}_1)^T \\ \operatorname{Aug}(\vec{x}_2)^T \\ \dots \\ \operatorname{Aug}(\vec{x}_n)^T \end{bmatrix}$$

and observation vector to solve the normal equations

$$X^T X \vec{w}^* = X^T \vec{y}$$

to find the optimal parameter vector.

#### Terminology for parameters

- ▶ With *d* features,  $\vec{w}$  has *d* + 1 entries.
- $\blacktriangleright$   $w_0$  is the **bias**, also known as the **intercept**.
- ▶ w<sub>1</sub>,..., w<sub>d</sub> each give the weight, i.e. coefficient, of a feature.

$$H(\vec{x}) = w_0 + w_1 x^{(1)} + \dots + w_d x^{(d)}$$

**Interpreting parameters** 

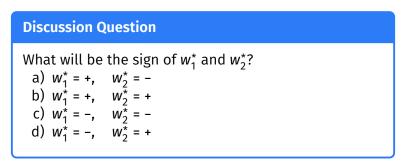
# Example: predicting sales

- For each of 26 stores, we have:
  - net sales,
  - square feet,
  - inventory,
  - advertising expenditure,
  - district size, and
  - number of competing stores.
- Goal: predict net sales given these features
- To begin:

 $H(\text{square feet, competitors}) = w_0 + w_1(\text{square feet}) + w_2(\text{competitors})$ 

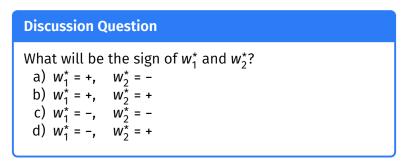
### **Example: predicting sales**

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Let's try it out ourselves. Follow along here.

#### Which features are most "important"?

#### **Discussion Question**

Which feature has the greatest effect on the outcome?

a) square feet:  $w_1^* = 16.202$ b) competitors:  $w_2^* = -5.311$ c) inventory:  $w_2^* = 0.175$ d) advertising:  $w_3^* = 11.526$ e) district size:  $w_4^* = 13.580$ 

### Which features are most "important"?

- The most important feature is not necessarily the feature with largest weight.
- ► Features are measured in different units, scales.
  - Suppose I fit one prediction rule, H<sub>1</sub>, with sales in dollars, and another prediction rule, H<sub>2</sub>, with sales in thousands of dollars.
  - Sales is just as important in both prediction rules.
  - But the weight of sales in H<sub>1</sub> will be 1000 times smaller than the weight of sales in H<sub>2</sub>.
  - Intuitive explanation: 5 × 45000 = (5 × 1000) × 45.
- Solution: before doing regression, standardize each feature, i.e. convert each feature to standard units.

#### **Standard units**

Recall: to convert a feature x<sub>1</sub>, x<sub>2</sub>, ..., x<sub>n</sub> to standard units, we use the formula

$$x_i$$
 in standard units =  $\frac{x_i - \bar{x}}{\sigma_x}$ 

Mean:

Standard deviation:

Standardized data:

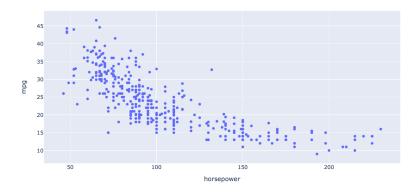
### Standard units for multiple linear regression

- The result of standardizing each feature (separately!) is that the units of each feature are on the same scale.
  - There's no need to standardize the outcome (net sales), since it's not being compared to anything.
- Then, solve the normal equations. The resulting w<sub>0</sub><sup>\*</sup>, w<sub>1</sub><sup>\*</sup>, ..., w<sub>d</sub><sup>\*</sup> are called the standardized regression coefficients.
- Standardized regression coefficients can be directly compared to one another.

Let's try it out in our demo notebook.

Feature engineering

#### MPG vs. Horsepower



**Question:** Would a linear prediction rule work well on this dataset?

# A quadratic prediction rule

It looks like there's some sort of quadratic relationship between horsepower and mpg in the last scatter plot. We want to try and fit a prediction rule of the form

$$H(x) = W_0 + W_1 x + W_2 x^2$$

- Note that while this is quadratic in horsepower, it is linear in the parameters!
- We can do that, by choosing our two "features" to be x<sub>i</sub> and x<sub>i</sub><sup>2</sup>, respectively.

► In other words,  $x_i^{(1)} = x_i$  and  $x_i^{(2)} = x_i^2$ .

More generally, we can create new features out of existing features.

### A quadratic prediction rule

• Desired prediction rule: 
$$H(x) = w_0 + w_1 x + w_2 x^2$$
.

► The resulting design matrix looks like this:

$$X = \begin{bmatrix} 1 & x_1 & x_1^2 \\ 1 & x_2 & x_2^2 \\ \dots & & \\ 1 & x_n & x_n^2 \end{bmatrix}$$

To find optimal parameter vector w<sup>\*</sup>: solve the normal equations!

$$X^T X w^* = X^T y$$

#### More examples

What if we want to use a prediction rule of the form  $H(x) = w_0 + w_1 x + w_2 x^2 + w_3 x^3$ ?

What if we want to use a prediction rule of the form  $H(x) = w_1 \frac{1}{x^2} + w_2 \sin x + w_3 e^x$ ?

#### Feature engineering

- More generally, we can create new features out of existing information in our dataset. This process is called feature engineering.
  - In this class, feature engineering will mostly be restricted to creating non-linear functions of existing features (as in the previous example).
  - In the future you'll learn how to do other things, like encode categorical information.

#### Summary

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- The normal equations can be used to solve the multiple linear regression problem, where we use multiple features to predict an outcome.
- We can interpret the parameters as weights. The signs of weights give meaningful information, but we can only compare weights if our features are standardized.
- We can create non-linear features out of existing features. This process is called feature engineering.
  - A prediction rule only needs to be a linear function of the parameters for us to use linear regression. It does not need to be a linear function of the features.