Module 14 - Clustering



DSC 40A, Summer 2023

Agenda

- The clustering problem.
- k-Means Clustering algorithm.
- Why does k-Means work?
- Practical considerations.

The clustering problem

Question: how might we "cluster" these points into groups?



Problem statement: clustering

Goal: Given a list of *n* data points, stored as vectors in \mathbb{R}^d , $\vec{x}_1, \vec{x}_2, ..., \vec{x}_n$, and a positive integer *k*, **place the data points into** *k* groups of nearby points.

- These groups are called "clusters".
- Think about groups as types.
 - i.e., the goal of clustering is to assign each point a type, such that points of the same type (i.e. having similar attributes) are close to one another.
- Note, unlike with regression, there is no "right answer" that we are trying to predict — there is no y!
 - Clustering is an unsupervised method.

How do we define a group?

One solution: pick k cluster centers, i.e. centroids:

 $\vec{\mu}_1, \vec{\mu}_2, ..., \vec{\mu}_k$ in \mathbb{R}^d

- These *k* centroids define the *k* groups.
- Each data point "belongs" to the group corresponding to the nearest centroid.
- This reduces our problem from being "find the best group for each data point" to being "find the best locations for the centroids".



How do we pick the centroids?

- Let's come up with an cost function, C, which describes how good a set of centroids is.
 - Cost functions are a generalization of empirical risk functions.
- One possible cost function:

 $C(\mu_1, \mu_2, ..., \mu_k)$ = total squared distance of each data point \vec{x}_i to its closest centroid μ_j

- This C has a special name, inertia.
- Lower values of C lead to "better" clusterings.
 - ► **Goal:** Find the centroids $\mu_1, \mu_2, ..., \mu_k$ that minimize C.

Discussion Question

Suppose we have *n* data points, $\vec{x}_1, \vec{x}_2, ..., \vec{x}_n$, each of which are in \mathbb{R}^d .

Suppose we want to cluster our dataset into *k* clusters. How many ways can we assign points to clusters?



How do we minimize inertia?

- Problem: there are exponentially many possible clusterings. It would take too long to try them all.
- Another Problem: we can't use calculus or algebra to minimize C, since inertia is a piece-wise function so not differentiable at every point. It is a combinatorial problem of group assignment, so non-convex with multiple local minima.
- We need another solution.

k-Means Clustering

k-Means Clustering, i.e. Lloyd's Algorithm

Here's an algorithm that attempts to minimize inertia:

- 1. Pick a value of k and randomly initialize k centroids.
- 2. Keep the centroids fixed, and update the groups.

Assign each point to the nearest centroid.

3. Keep the groups fixed, and update the centroids.

Move each centroid to the center of its group.

4. Repeat steps 2 and 3 until the centroids stop changing. Mile loop break condition

Example

See the following site for an interactive visualization of k-Means Clustering: https://tinyurl.com/40akmeans

An example by hand

Suppose we choose the initial centroids $\mu_1 = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$ and $\mu_2 = \begin{bmatrix} 3 \\ 4 \end{bmatrix}$. Where will the centroids move to after one iteration of k-Means Clustering?



Demo

Let's see k-Means Clustering in action. Follow along here.

Why does k-Means work?

What is the goal of k-Means Clustering?

Recall, our goal is to find the centroids $\mu_1, \mu_2, ..., \mu_k$ that minimize inertia:

$$C(\mu_1, \mu_2, ..., \mu_k) = \text{ total squared distance of each}$$

data point \vec{x}_i to its
closest centroid μ_i

Let's argue that each step of the k-Means Clustering algorithm reduces inertia. J you'r only demostry of each step
 After enough iterations, inertia will be small enough, smiller than

Why does k-Means work? (Step 1)

Step 1: Pick a value of *k* and randomly initialize *k* centroids.

After initializing our k centroids, we have an initial value of inertia. We are going to argue that this only decreases.

Why does k-Means work? (Step 2)

Step 2: Keep the centroids fixed, and update the groups by assigning each point to the nearest centroid.

- Assuming the centroids are fixed, for each x_i we have a choice — which group should it be a part of?
- Whichever group we choose, inertia will be calculated using the squared distance between \vec{x}_i and that group's centroid.
- Thus, to minimize inertia, we assign each \vec{x}_i to the group corresponding to the closest centroid.

Note that this analysis holds every time we're at Step 2, not just the first time.

Why does k-Means work? (Step 3)

Step 3: Keep the groups fixed, and update the centroids by moving each centroid to the center of its group (by averaging coordinates).

Before we justify why this is optimal, let's revisit inertia.

Aside: separating inertia

Inertia:

$$C(\mu_1, \mu_2, ..., \mu_k)$$
 = total squared distance of each
data point \vec{x}_i to its
closest centroid μ_i

Note that an equivalent way to write inertia is

$$C(\mu_1, \mu_2, ..., \mu_k) = C(\mu_1) + C(\mu_2) + ... + C(\mu_k) \text{ where}$$

$$C(\mu_j) = \text{total squared distance of each}$$

$$data \text{ point } \vec{x}_i \text{ in group } j$$

$$to \text{ centroid } \mu_j$$

▶ What's the point?

Why does k-Means work? (Step 3)

$$\begin{split} C(\mu_1, \mu_2, ..., \mu_k) &= C(\mu_1) + C(\mu_2) + ... + C(\mu_k) & \text{where} \\ C(\mu_j) &= \text{total squared distance of each data point } \vec{x}_i \\ & \text{in group } j \text{ to centroid } \mu_j \end{split}$$

Step 3: Keep the groups fixed, and update the centroids by moving each centroid to the center of its group (by averaging coordinates).

• Let's argue why this minimizes $C(\mu_i)$, for each group *j*.

Why does k-Means work? (Step 3)

 $C(\mu_j)$ = total squared distance of each data point \vec{x}_i in group *j* to centroid μ_j

Suppose group *j* contains the points (4, 3), (6, 4), and (8, 2). Where should we put $\mu_j = \begin{bmatrix} a \\ b \end{bmatrix}$ to minimize $C(\mu_j)$?



Why does k-Means work? (Step 3) $((a,b) = (4-a)^{2} + (3-b)^{2} + (8-a)^{2} + (2-b)^{2} + (6-a)^{2} + (4-b)^{2}$

 $\frac{\partial c}{\partial a} = -2(4-a) + -2(8-a) + -2(6-a) = 0$

4-a 78-a + 6-a = 0



Why does k-Means work? (Step 3)

 $C(\mu_j)$ = total squared distance of each data point \vec{x}_i in group *j* to centroid μ_j

Suppose group *j* contains the points (4, 3), (6, 4), and (8, 2). Where should we put $\mu_j = \begin{bmatrix} a \\ b \end{bmatrix}$ to minimize $C(\mu_j)$?



Cost and empirical risk

On the previous slide, we saw a function of the form

$$\begin{split} C(\mu_j) &= C(a,b) = (4-a)^2 + (3-b)^2 \\ &+ (6-a)^2 + (4-b)^2 \\ &+ (8-a)^2 + (2-b)^2 \end{split}$$

- C(a, b) can be thought of as the sum of two separate functions, f(a) and g(b).
 - ► $f(a) = (4 a)^2 + (6 a)^2 + (8 a)^2$ computes the total squared distance of each x_1 coordinate to a.
 - From earlier in the course, we know that $a^* = \frac{4+6+8}{3} = 6$ minimizes f(a).

Practical considerations

Initialization

- Depending on our initial centroids, k-Means may "converge" to a clustering that doesn't actually have the lowest possible inertia.
 - In other words, like gradient descent, k-Means can get caught in a local minimum.
- Some solutions:
 - Run k-Means several times, each with different randomly chosen initial centroids. Keep track of the inertia of the final result in each attempt. Choose the attempt with the lowest inertia.
 - k-Means++: choose one initial centroid at random, and place other centroids far from all other centroids. Ly K-medicios: medican based, robust to outlier fuzzy C-mens: folks in multiple groups

Choosing k

- Note that as *k* increases, inertia decreases.
 - Intuitively, as we add more centroids, the distance between each point and its closest centroid will drop.
- But the goal of clustering is to put data points into groups, and having a large number of groups may not be meaningful.
- ▶ This suggests a tradeoff between *k* and inertia.

The "elbow" method

- Strategy: run k-Means Clustering for many choices of k (e.g. k = 1, 2, 3, ..., 8).
- Compute the value of inertia for each resulting set of centroids.
- Plot a graph of inertia vs k.
- Choose the value of k that appears at an "elbow".



See the notebook for a demo.

Low inertia isn't everything!

- Even if k-Means works as intended and finds the choice of centroids that minimize inertia, the resulting clustering may not look "right" to us humans.
 - Recall, inertia measures the total squared distance to centroids.
 - This metric doesn't always match our intuition.
- Let's look at some examples at https://tinyurl.com/40akmeans.
 - ▶ Go to "I'll Choose" and "Smiley Face". Good luck!



Other clustering techniques

- k-Means Clustering is just one way to cluster data.
- There are many others, each of which work differently and produce different kinds of results.
- Another common technique: agglomerative clustering.
 - High level: start out with each point being in its own cluster. Repeatedly combine clusters until only k are left.



Summary

- ▶ k-Means Clustering attempts to minimize inertia.
 - We showed that it minimizes inertia at each step, but it's possible that it converges to a local minimum.
 - Different initial centroids can lead to different clusterings.
- ► To choose k, the number of clusters, we can use the elbow method. → Hink of this as ceiling for k
- Next time: switching gears to probability and combinatorics.