

Lecture 3

# Empirical Risk Minimization - mean absolute error

DSC 40A, Fall 2024

# Announcements

- Groupwork 1 due Friday.

# Agenda

- Recap: Mean squared error.
- Another loss function.
- Minimizing mean absolute error.

Question 🤔

Answer at [q.dsc40a.com](https://q.dsc40a.com)

Remember, you can always ask questions at [q.dsc40a.com](https://q.dsc40a.com)!

## The modeling recipe

We've implicitly introduced a three-step process for finding optimal model parameters (like  $h^*$ ) that we can use for making predictions:

1. Choose a model.

$$H(x) = h$$

Another choice:  $H(x) = v_0 + w_1 x$

2. Choose a loss function.

$$L_{sq}(y_i, h) = (y_i - h)^2$$

Another choice?

3. Minimize average loss to find optimal model parameters.

$$h^* = \text{Mean} \{y_1, \dots, y_n\}$$

Another optimal model  $h^*$ ?

# Recap: Mean squared error

## Minimizing using calculus

We'd like to minimize:

$$\text{MSE} = R_{\text{sq}}(h) = \frac{1}{n} \sum_{i=1}^n \underbrace{(y_i - h)^2}_{L_{\text{sq}}(y_i, h)}$$

In order to minimize  $R_{\text{sq}}(h)$ , we:

1. take its derivative with respect to  $h$ ,
2. set it equal to 0,
3. solve for the resulting  $h^*$ , and
4. perform a second derivative test to ensure we found a minimum.

## The mean minimizes mean squared error!

- The problem we set out to solve was, find the  $h^*$  that minimizes:

$$R_{\text{sq}}(h) = \frac{1}{n} \sum_{i=1}^n (y_i - h)^2$$

- The answer is:

$$h^* = \text{Mean}(y_1, y_2, \dots, y_n)$$

- The **best constant prediction**, in terms of mean squared error, is always the **mean**.
- This answer is always unique!
- We call  $h^*$  our **optimal model parameter**, for when we use:
  - the constant model,  $H(x) = h$ , and
  - the squared loss function,  $L_{\text{sq}}(\overbrace{y_i}, h) = (y_i - h)^2$ .



## Bonus: the mean is easy to compute

```
def mean(numbers):  
    total = 0  
    for number in numbers:  
        total = total + number  
    return total / len(numbers)
```

- Time complexity  $\Theta(n)$

40B

## Aside: Notation

Another way of writing

$h^*$  is the value of  $h$  that minimizes  $\frac{1}{n} \sum_{i=1}^n (y_i - h)^2$

is

$$h^* = \operatorname{argmin}_h \left( \frac{1}{n} \sum_{i=1}^n (y_i - h)^2 \right)$$

↳ argument that minimizes

$h^*$  is the solution to an optimization problem.

# Another loss function

## Another loss function

- Last lecture, we started by computing the **error** for each of our **predictions**, but ran into the issue that some errors were positive and some were negative.

$$e_i = \underbrace{y_i}_{\text{data we have}} - \underbrace{H(x_i)}_{\text{prediction}} \quad H(x_i)$$

- The solution was to **square** the errors, so that all are non-negative. The resulting loss function is called **squared loss**.

$$L_{\text{sq}}(y_i, H(x_i)) = (y_i - H(x_i))^2$$

- Another loss function, which also measures how far  $H(x_i)$  is from  $y_i$ , is **absolute loss**.

$$L_{\text{abs}}(y_i, H(x_i)) = |y_i - H(x_i)| \geq 0$$

80 minimized avg sq loss  
but not necessarily abs loss

## Squared loss vs. absolute loss

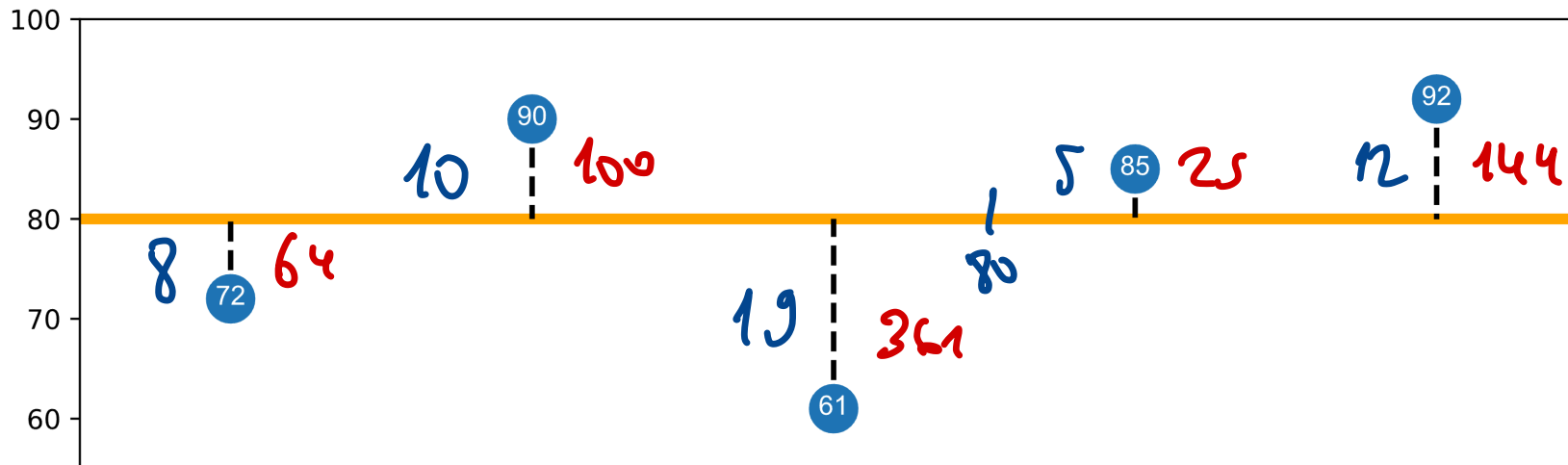
For the constant model,  $H(x_i) = h$ , so we can simplify our loss functions as follows:

- Squared loss:  $L_{\text{sq}}(y_i, h) = (y_i - h)^2$ .
- Absolute loss:  $L_{\text{abs}}(y_i, h) = |y_i - h|$ .

mean  
↑

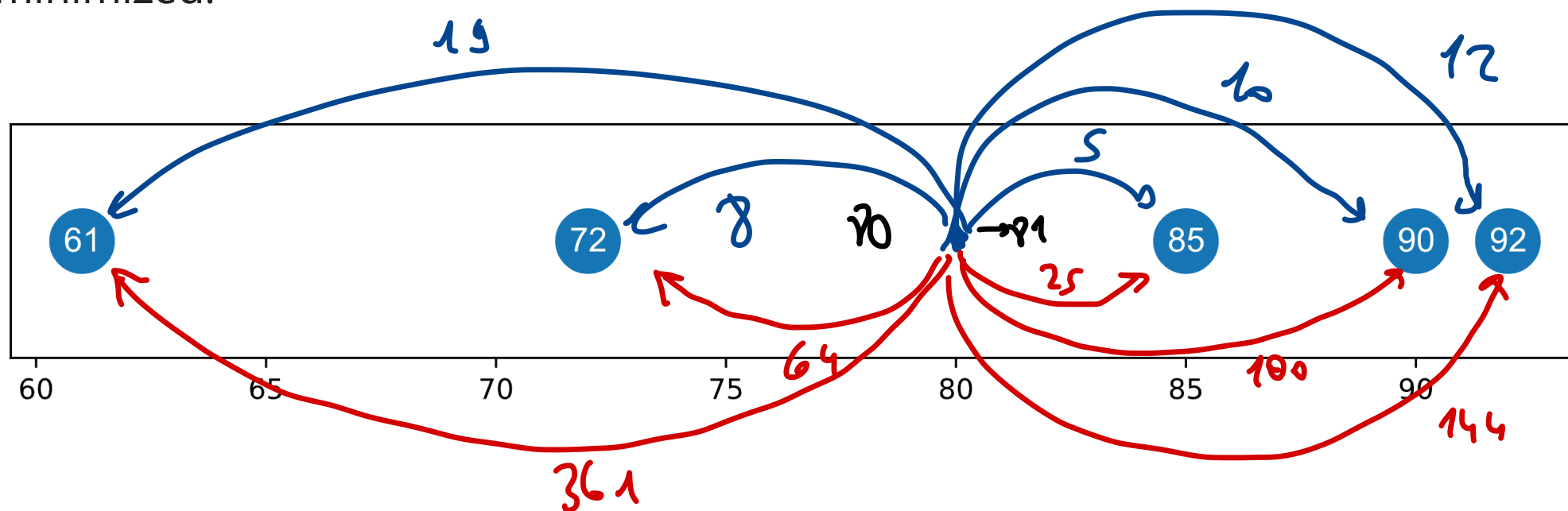
Consider, again, our example dataset of five commute times and the prediction  $h = 80$ .

$$y_1 = 72 \quad y_2 = 90 \quad y_3 = 61 \quad y_4 = 85 \quad y_5 = 92$$



## Squared loss vs. absolute loss

- When we use squared loss,  $h^*$  is the point at which the average squared loss is minimized.
- When we use absolute loss,  $h^*$  is the point at which the average absolute loss is minimized.



## Mean absolute error

- Suppose we collect  $n$  commute times,  $y_1, y_2, \dots, y_n$ .
- The average absolute loss, or mean absolute error (MAE), of the prediction  $h$  is:

$$R_{\text{abs}}(h) = \frac{1}{n} \sum_{i=1}^n \overbrace{|y_i - h|}^{\mathcal{L}_{\text{abs}}(y_i, h)}$$

- We'd like to find the best prediction,  $h^*$ .
- Previously, when using squared loss we used calculus to find the optimal model parameter  $h^*$  that minimized  $R_{\text{sq}}$ .
- Can we use calculus to minimize  $R_{\text{abs}}(h)$ , too?

# Minimizing mean absolute error



## Minimizing using calculus, again

We'd like to minimize:

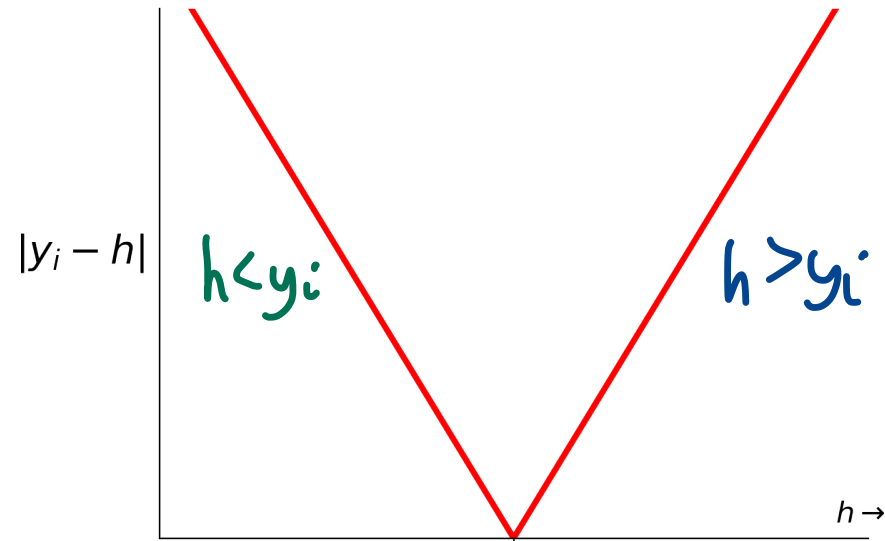
$$R_{\text{abs}}(h) = \frac{1}{n} \sum_{i=1}^n |y_i - h|$$

In order to minimize  $R_{\text{abs}}(h)$ , we:

1. take its derivative with respect to  $h$ ,
2. set it equal to 0,
3. solve for the resulting  $h^*$ , and
4. perform a second derivative test to ensure we found a minimum.

find derivative of  
 $L_{\text{abs}}(y_i, h)$

## Step 0: The derivative of $|y_i - h|$



when  $h = y_i$

$$|h - y_i| = |y_i - h| = 0$$

Remember that  $|x|$  is a **piecewise linear** function of  $x$ :

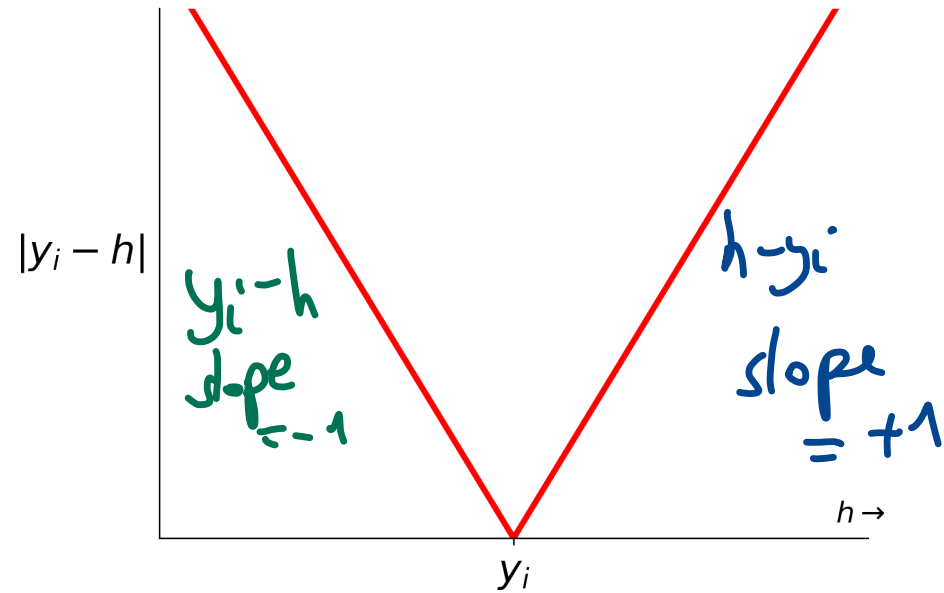
$$|x| = \begin{cases} x & x > 0 \\ 0 & x = 0 \\ -x & x < 0 \end{cases}$$

So,  $|y_i - h|$  is also a piecewise linear function of  $h$ :

$$|y_i - h| = \begin{cases} y_i - h & h < y_i \\ 0 & y_i = h \\ h - y_i & h > y_i \end{cases}$$

$$\begin{aligned} \text{if } y_i - h < 0 \\ h - y_i > 0 \end{aligned}$$

## Step 0: The "derivative" of $|y_i - h|$



$$|y_i - h| = \begin{cases} y_i - h & h < y_i \\ 0 & y_i = h \\ h - y_i & h > y_i \end{cases}$$

What is  $\frac{d}{dh} |y_i - h|$ ?

$$\frac{d}{dh} |y_i - h| = \begin{cases} -1 & , h < y_i \\ \text{undefined} & , h = y_i \\ +1 & , h > y_i \end{cases}$$

ignore for now!

# Step 1: The "derivative" of $R_{\text{abs}}(h)$

$$\frac{d}{dh} |y_i - h| = \begin{cases} -1 & y_i > h \\ \text{undefined} & y_i = h \\ +1 & y_i < h \end{cases}$$

$$\frac{d}{dh} R_{\text{abs}}(h) = \frac{d}{dh} \left( \frac{1}{n} \sum_{i=1}^n |y_i - h| \right)$$

$$= \frac{1}{n} \sum_{i=1}^n \frac{d}{dh} |y_i - h|$$

this is a sum of +1's and -1's

$$= \frac{1}{n} \left[ \underbrace{\#(h > y_i)}_{+1} - \#(h < y_i) \right]$$

we add +1 when  $h > y_i$

we subtract 1 when  $h < y_i$

Example 61 72 85 80 91  
 $h=80$

$$\frac{d}{dh} R_{\text{abs}}(80) = \frac{2-3}{5} = -\frac{1}{5}$$

## Question 🤔

Answer at [q.dsc40a.com](http://q.dsc40a.com)

The slope of  $R_{\text{abs}}$  at  $h$  is

$$\frac{1}{n} [(\# \text{ of } y_i < h) - (\# \text{ of } y_i > h)]$$

Suppose that the number of points  $n$  is odd. At what value of  $h$  does the slope change from negative to positive?

- A)  $h = \text{mean of } \{y_1, \dots, y_n\}$
- B)  $h = \underline{\text{median of } \{y_1, \dots, y_n\}}$  ←
- C)  $h = \text{mode of } \{y_1, \dots, y_n\}$

Steps 2 and 3: Set to 0 and solve for the minimizer,  $h^*$

$$\frac{d}{dh} R_{abs}(h) = \frac{1}{n} [\#(h > y_i) - \#(h < y_i)] = 0$$

$$\#(h > y_i) = \#(h < y_i)$$

We want  $h^*$  is the value where the  
number of data pts to left of  $h$   
= number of data pts to right of  $h$   $\Rightarrow$  median!

## The median minimizes mean absolute error!

- The new problem we set out to solve was, find the  $h^*$  that minimizes:

$$R_{\text{abs}}(h) = \frac{1}{n} \sum_{i=1}^n |y_i - h|$$

- The answer is:

$$h^* = \text{Median}(y_1, y_2, \dots, y_n)$$

- This is because the median has an equal number of data points to the left of it and to the right of it.
- To make a bit more sense of this result, let's graph  $R_{\text{abs}}(h)$ .

# Visualizing mean absolute error

$$= \frac{1}{5} \left[ \begin{array}{c} \text{V} \\ 72 \end{array} + \begin{array}{c} \text{V} \\ 90 \end{array} + \begin{array}{c} \text{V} \\ 61 \end{array} + \begin{array}{c} \text{V} \\ 85 \end{array} + \begin{array}{c} \text{V} \\ 92 \end{array} \right]$$

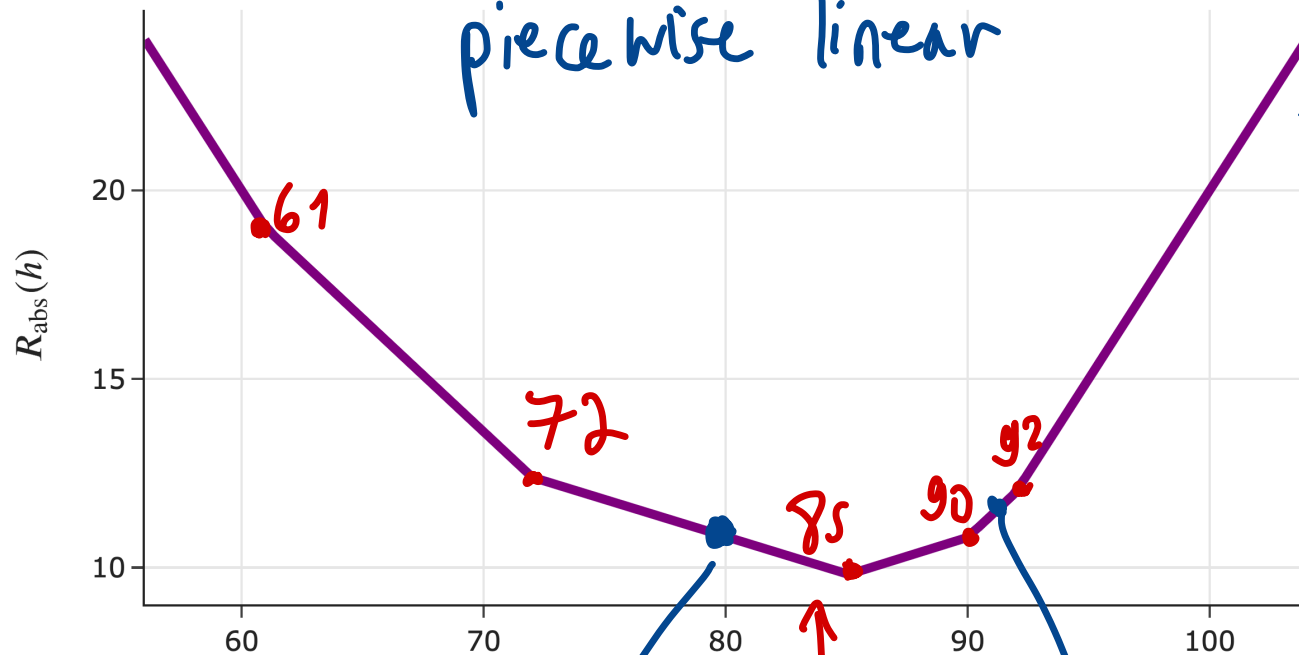
$$R_{\text{abs}}(h) = \frac{1}{5} (|72 - h| + |90 - h| + |61 - h| + |85 - h| + |92 - h|)$$

piecewise linear

Consider, again, our example dataset of five commute times.

72, 90, 61, 85, 92

Where are the "bends" in the graph of  $R_{\text{abs}}(h)$  – that is, where does its slope change?



$$\frac{d}{dh} R_{\text{abs}}(80) = \frac{2-3}{5} = -\frac{1}{5}$$

$h^* = \text{median}$

$$\frac{d}{dh} R_{\text{abs}}(91) = \frac{4-1}{5} = \frac{3}{5}$$



## Question 🤔

Answer at [q.dsc40a.com](https://q.dsc40a.com)

Consider, again, our example dataset of five commute times.

72, 90, 61, 85, 92

Suppose we add a sixth point so that our data is now

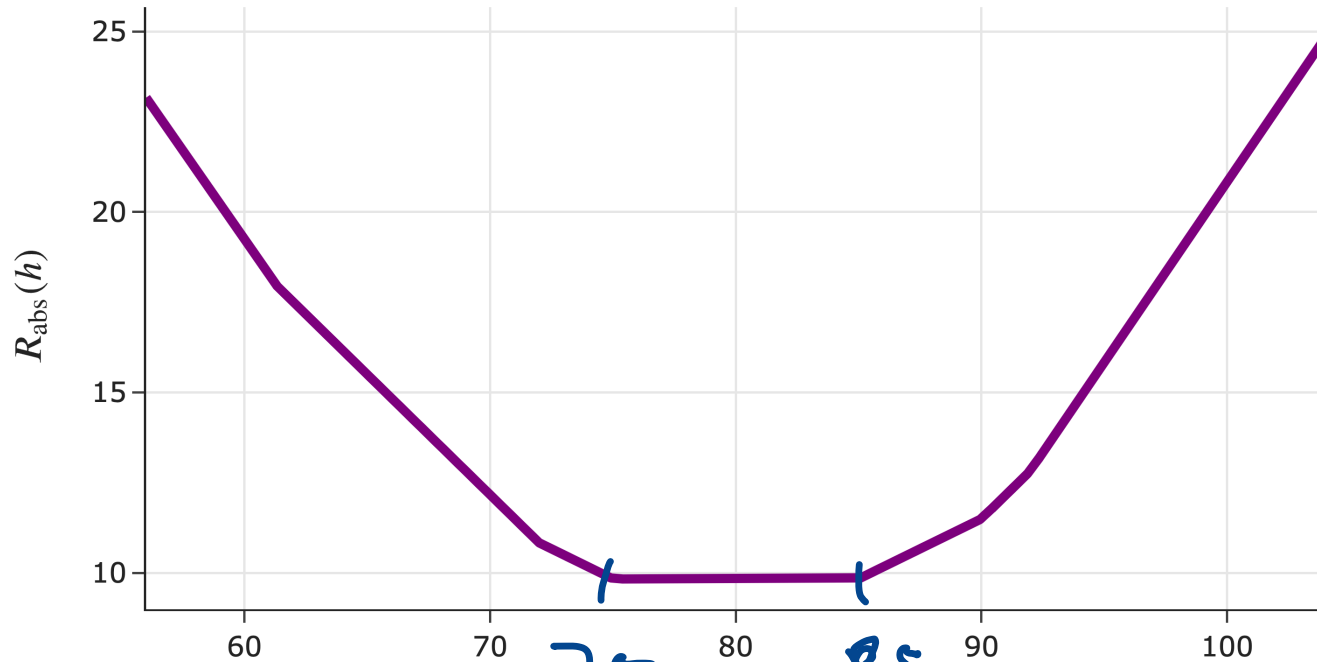
72, 90, 61, 85, 92, 75

Which of the following correctly describes the  $h^*$  that minimizes mean absolute error for our new dataset?

- A) 85 only
- B) 75 only
- C) 80 only
- D) Any value between 75 and 85 inclusive

# Visualizing mean absolute error, with an even number of points

$$R_{\text{abs}}(h) = \frac{1}{6}(|72 - h| + |90 - h| + |61 - h| + |85 - h| + |92 - h| + |75 - h|)$$



What if we add a sixth data point?

72, 90, 61, 85, 92, 75

Is there a unique  $h^*$ ?

not unique if  $n$  is even  
 $R_{\text{abs}}(h) = R_{\text{abs}}(h^*)$  for all  $75 \leq h \leq 85$

## The median minimizes mean absolute error!

- The new problem we set out to solve was, find the  $h^*$  that minimizes:

$$R_{\text{abs}}(h) = \frac{1}{n} \sum_{i=1}^n |y_i - h|$$

- The answer is:

$$h^* = \text{Median}(y_1, y_2, \dots, y_n)$$

The **best constant prediction**, in terms of mean absolute error, is always the **median**.

- When  $n$  is odd, this answer is unique.
- When  $n$  is even, any number between the middle two data points (when sorted) also minimizes mean absolute error.
- When  $n$  is even, define the median to be the mean of the middle two data points.

## The modeling recipe, again

We've now made two full passes through our "modeling recipe."

1. Choose a model.
2. Choose a loss function.
3. Minimize average loss to find optimal model parameters.

## Empirical risk minimization

- The formal name for the process of minimizing average loss is **empirical risk minimization**.
- Another name for "average loss" is **empirical risk**.
- When we use the squared loss function,  $L_{\text{sq}}(y_i, h) = (y_i - h)^2$ , the corresponding empirical risk is mean squared error:

$$R_{\text{sq}}(h) = \frac{1}{n} \sum_{i=1}^n (y_i - h)^2$$

- When we use the absolute loss function,  $L_{\text{abs}}(y_i, h) = |y_i - h|$ , the corresponding empirical risk is mean absolute error:

$$R_{\text{abs}}(h) = \frac{1}{n} \sum_{i=1}^n |y_i - h|$$

## Empirical risk minimization, in general

Key idea: If  $L(y_i, h)$  is any loss function, the corresponding empirical risk is:

$$R(h) = \frac{1}{n} \sum_{i=1}^n L(y_i, h)$$

Question 🤔

Answer at [q.dsc40a.com](http://q.dsc40a.com)

What questions do you have?

## Summary, next time

- $h^* = \text{Mean}(y_1, y_2, \dots, y_n)$  minimizes mean squared error,  
 $R_{\text{sq}}(h) = \frac{1}{n} \sum_{i=1}^n (y_i - h)^2$ .
- $h^* = \text{Median}(y_1, y_2, \dots, y_n)$  minimizes mean absolute error,  
 $R_{\text{abs}}(h) = \frac{1}{n} \sum_{i=1}^n |y_i - h|$ .
- $R_{\text{sq}}(h)$  and  $R_{\text{abs}}(h)$  are examples of **empirical risk** – that is, average loss.
- **Next time:** What's the relationship between the mean and median? What is the significance of  $R_{\text{sq}}(h^*)$  and  $R_{\text{abs}}(h^*)$ ?

Shana tova to those celebrating!

