Lecture 5

# Simple Linear Regression

DSC 40A, Fall 2024

#### Announcements

- Homework 1 is due Friday night.
- Look at the office hours schedule here and plan to start regularly attending!
- Remember to take a look at the supplementary readings linked on the course website.

# Agenda

- 0-1 loss
- Predictin rules using features
- Simple linear regression.
- Minimizing mean squared error for the simple linear model.



Answer at q.dsc40a.com

#### Remember, you can always ask questions at q.dsc40a.com!

If the direct link doesn't work, click the " Electure Questions"
link in the top right corner of dsc40a.com.

#### Another example: 0-1 loss

Consider, for example, the **0-1 loss**:

$$L_{0,1}(y_i,h) = egin{cases} 0 & y_i = h \ 1 & y_i 
eq h \end{cases}$$

The corresponding empirical risk is:

$$R_{0,1}(h) = rac{1}{n}\sum_{i=1}^n L_{0,1}(y_i,h)$$



#### Answer at q.dsc40a.com

$$R_{0,1}(h)=rac{1}{n}\sum_{i=1}^negin{cases} 0 & y_i=h\ 1 & y_i
eq h \end{cases}$$

Suppose  $y_1, y_2, \ldots, y_n$  are all unique. What is  $R_{0,1}(y_1)$ ?

- A. O.
- B.  $\frac{1}{n}$ .
- C.  $\frac{n-1}{n}$ .
- D. 1.

## Minimizing empirical risk for 0-1 loss

$$R_{0,1}(h)=rac{1}{n}\sum_{i=1}^negin{cases} 0 & y_i=h\ 1 & y_i
eq h \end{cases}$$

# Summary: Choosing a loss function

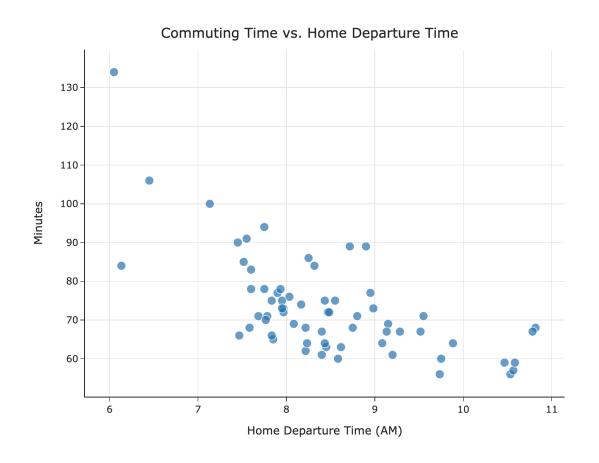
Key idea: Different loss functions lead to different best predictions,  $h^*$ !

Loss	Minimizer	Always Unique?	Robust to Outliers?	Differentiable?
$L_{ m sq}$	mean	yes 🗸	no 🗙	yes 🗸
$L_{ m abs}$	median	no 🗙	yes 🗸	no 🗙
$L_\infty$	midrange	yes 🗸	no 🗙	no 🗙
$L_{0,1}$	mode	no 🗙	yes 🗸	no 🗙

The optimal predictions,  $h^*$ , are all **summary statistics** that measure the **center** of the dataset in different ways.

# **Predictions with features**

#### Towards simple linear regression

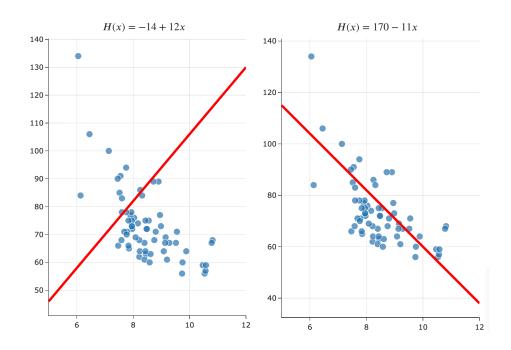


- In Lecture 1, we introduced the idea of a hypothesis function, H(x).
- We've focused on finding the best constant model, H(x) = h.
- Now that we understand the modeling recipe, we can apply it to find the best simple linear regression model,  $H(x) = w_0 + w_1 x.$
- This will allow us to make predictions that aren't all the same for every data point.

# **Recap: Hypothesis functions and parameters**

A hypothesis function, H, takes in an x as input and returns a predicted y. **Parameters** define the relationship between the input and output of a hypothesis function.

The simple linear regression model,  $H(x) = w_0 + w_1 x$ , has two parameters:  $w_0$  and  $w_1$ .



# The modeling recipe

1. Choose a model.

2. Choose a loss function.

3. Minimize average loss to find optimal model parameters.

#### Features

A feature is an attribute of the data – a piece of information.

- Numerical: maximum allowed speed, time of departure
- Categorical: day of week
- Boolean: was there a car accident on the road?

Think of features as columns in a DataFrame (i.e. table).

(add figure)

# Variables

- The features, *x*, that we base our predictions on are called predictor variables.
- The quantity, *y*, that we're trying to predict based on these features is called the response variable, dependent variable or target.
- We are trying to predict our commute time as a function of departure time.

# Modeling

- We believe that commute time is a function of departure time.
- I.e., there is a function H so that: commute time pprox H(departure time)
- H is called a hypothesis function or prediction rule.
- Our goal: find a good prediction rule, H.

## **Possible Hypothesis Functions**

- $H_1$ (departure time) = 90 10 ·(departure time-7)
- $H_2$ (departure time) = 90 (departure time-8)<sup>2</sup>
- $H_3$ (departure time) = 20 + 6·departure time

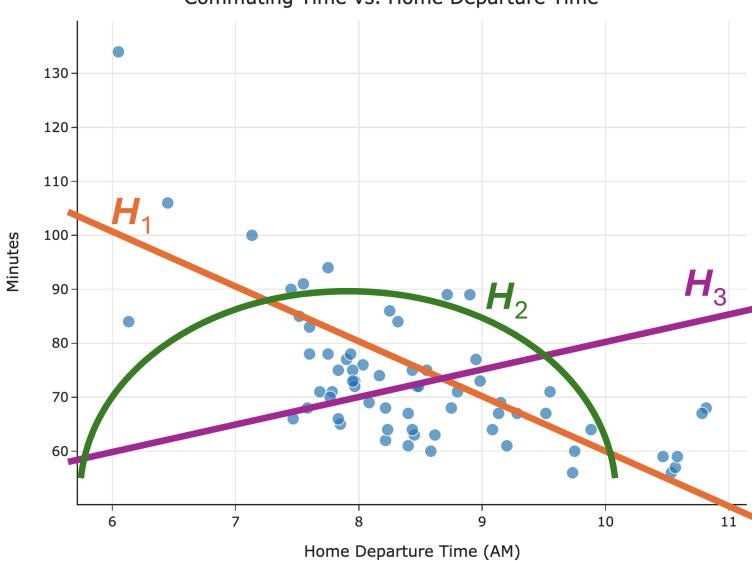
These are all valid prediction rules.

Some are better than others.

# **Comparing predictions**

- How do we know which is best:  $H_1, \ H_2, \ H_3$ ?
- We gather data from *n* days of commute. Let xi be experience, yi be salary:

• See which rule works better on data.



Commuting Time vs. Home Departure Time

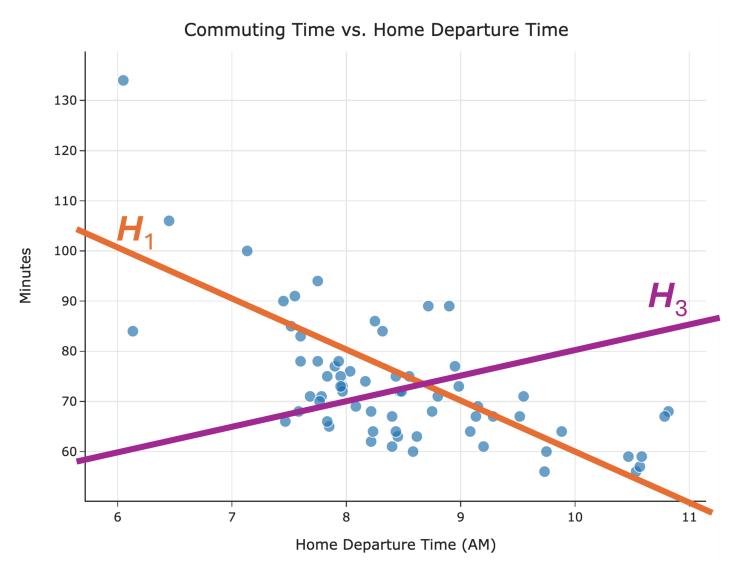
# Quantifying the performance of a model

- Reminder: one loss function, which measures how far  $H(x_i)$  is from  $y_i$ , is absolute loss.
- The mean absolute error of H(x) is

$$R_{\mathrm{abs}}(h) = rac{1}{n}\sum_{i=1}^n |y_i - H(x_i))|$$

- We want the **best** prediction,  $H^*(x)$ .
- The smaller  $R_{
  m abs}(h)$  is, the better the hypothesis.

#### Mean absolute error



# Finding the best hypothesis H(x)

- Goal: out of all functions  $\mathbb{R} \to \mathbb{R}$ , find the function H with the smallest mean absolute error.
- That is,  $H^*$  should be the function that minimizes

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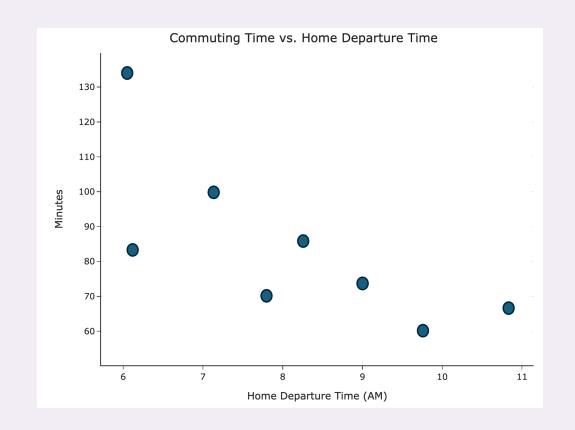
$$R_{\mathrm{abs}}(h) = rac{1}{n}\sum_{i=1}^n |y_i - H(x_i))|$$

• There are two problems with this.

# Question 😵 Answer at q.dsc40a.com

Given the data below, is there a prediction rule H which has zero mean absolute error?

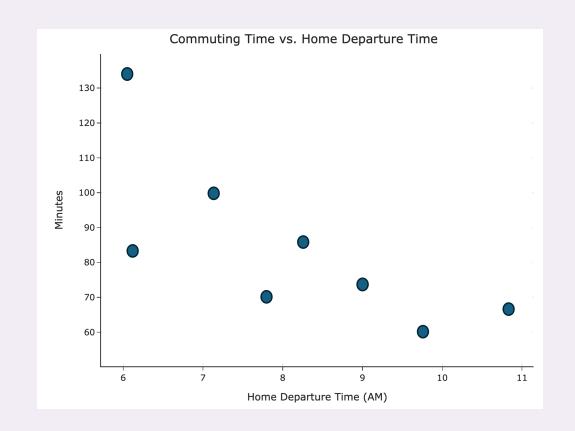
- A. yes
- B. no



# Question 😵 Answer at q.dsc40a.com

Given the data below, is there a prediction rule H which has zero mean absolute error?

- A. yes
- B. no



# Problem

- We can make mean absolute error very small, even zero!
- But the function will be weird.
- This is called **overfitting**.
- Remember our real goal: make good predictions on data we haven't seen.

# Solution

- Don't allow *H* to be just any function.
- Require that it has a certain form.
- Examples:
  - $\circ$  Linear:  $H(x)=w_0+w_1x_2$ .
  - $\circ~$  Quadratic:  $H(x)=w_0+w_1x_1+w_2x^2.$
  - $\circ\;$  Exponential:  $H(x)=w_0e^{w_1x}.$
  - $\circ\;$  Constant:  $H(x)=w_0.$

#### Finding the best linear model

- Goal: Out of all linear functions  $\mathbb{R} \to \mathbb{R}$ , find the function  $H^*$  with the smallest mean absolute error.
  - $\circ$  Linear functions are of the form  $H(x) = w_0 + w_1 x$ .
  - $\circ$  They are defined by a slope ( $w_1$ ) and intercept ( $w_0$ ).
- That is,  $H^*$  should be the linear function that minimizes

$$R_{\mathrm{abs}}(H) = rac{1}{n}\sum_{i=1}^n ig|y_i - H(x_i)ig|$$

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$$R_{ ext{abs}}(H) = rac{1}{n}\sum_{i=1}^n ig|y_i - H(x_i)ig|$$

• There is still a problem with this.

#### Problem #2

It is hard to minimize the mean absolute error:

$$R_{\mathrm{abs}}(H) = rac{1}{n}\sum_{i=1}^n \left|y_i - H(x_i)
ight|$$

- Not differentiable!
- What can we do?

# Minimizing mean squared error for the simple linear model

- We'll choose squared loss, since it's the easiest to minimize.
- Our goal, then, is to find the linear hypothesis function  $H^*(x)$  that minimizes empirical risk:

$$R_{ ext{sq}}(H) = rac{1}{n}\sum_{i=1}^n \left(y_i - H(x_i)
ight)^2$$

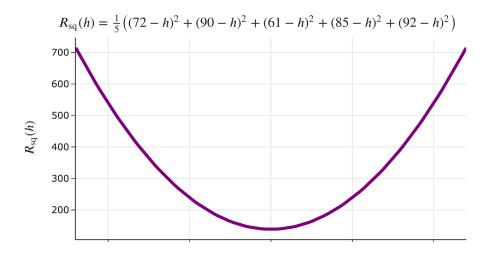
• Since linear hypothesis functions are of the form  $H(x)=w_0+w_1x$ , we can rewrite  $R_{
m sq}$  as a function of  $w_0$  and  $w_1$ :

$$R_{ ext{sq}}(w_0,w_1) = rac{1}{n}\sum_{i=1}^n \left(y_i - (w_0 + w_1 x_i))^2
ight|$$

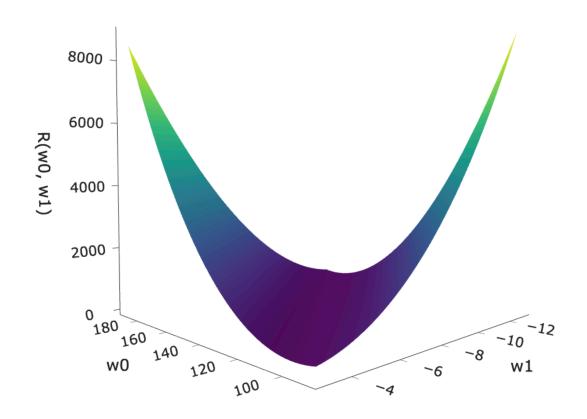
• How do we find the parameters  $w_0^*$  and  $w_1^*$  that minimize  $R_{
m sq}(w_0,w_1)$ ?

#### Loss surface

# For the constant model, the graph of $R_{ m sq}(h)$ looked like a parabola.



What does the graph of  $R_{
m sq}(w_0,w_1)$  look like for the simple linear regression model?



# Minimizing mean squared error for the simple linear model

# Minimizing multivariate functions

• Our goal is to find the parameters  $w_0^*$  and  $w_1^*$  that minimize mean squared error:

$$R_{ ext{sq}}(w_0,w_1) = rac{1}{n}\sum_{i=1}^n \left(y_i - (w_0 + w_1 x_i)
ight)^2$$

- $R_{
  m sq}$  is a function of two variables:  $w_0$  and  $w_1$ .
- To minimize a function of multiple variables:
  - Take partial derivatives with respect to each variable.
  - Set all partial derivatives to 0.
  - Solve the resulting system of equations.
  - Ensure that you've found a minimum, rather than a maximum or saddle point (using the second derivative test for multivariate functions).