

Lecture 13 continued

Feature engineering and transformations

DSC 40A, Fall 2024

The Midterm Exam is on Monday, Nov 4th!

- Randomized seat assignment is in the homework - look up your seat.
- 50 minutes, on paper, no calculators or electronics.
 - **You are allowed to bring one two-sided page of notes.**
- Content: Lectures 1-13, Homeworks 1-4, Groupworks 1-4.
- Prepare by practicing with old exam problems at practice.dsc40a.com.
 - Problems are sorted by topic!

Discussion will take place today
HW 4 due Friday
No HW due next week

How do we fit hypothesis functions that aren't linear in the parameters?

- Suppose we want to fit the hypothesis function:

$$H(x) = w_0 e^{w_1 x}$$

- This is **not** linear in terms of w_0 and w_1 , so our results for linear regression don't apply.
- **Possible solution:** Try to apply a **transformation**.

Goal: $w_0 + w_1 \cdot \square$

Transformations

- Question: Can we re-write $H(x) = w_0 e^{w_1 x}$ as a hypothesis function that is linear in the parameters?

$$y = w_0 e^{w_1 x}$$

/ $\log_e(\cdot)$

x	y	z = log(y)

$$\log y = \log(w_0 e^{w_1 x})$$

$$= \log w_0 + \log e^{w_1 x}$$

$$\log y = \log w_0 + w_1 x$$

$$z = \underline{b_0} + \underline{b_1} x$$

linear in the parameters

$$T(x) \approx z$$

$$H(x) = e^z \approx y$$

$$b_0 = \log w_0 \Rightarrow w_0 \approx e^{b_0}$$

Transformations

- **Solution:** Create a new hypothesis function, $T(x)$, with parameters b_0 and b_1 , where $T(x) = b_0 + b_1x$.
- This hypothesis function is related to $H(x)$ by the relationship $T(x) = \log H(x)$.
- \vec{b} is related to \vec{w} by $b_0 = \log w_0$ and $b_1 = w_1$.

- Our new observation vector, \vec{z} , is
$$\begin{bmatrix} \log y_1 \\ \log y_2 \\ \dots \\ \log y_n \end{bmatrix}.$$

$$X^T X \vec{b}^* = X^T \vec{z}$$

new observation vector

intermediate parameter vector

- $T(x) = b_0 + b_1x$ is linear in its parameters, b_0 and b_1 .
- Use the solution to the normal equations to find \vec{b}^* , and the relationship between \vec{b} and \vec{w} to find \vec{w}^* .

Once again, let's try it out! Follow along in [this notebook](#).

Non-linear hypothesis functions in general

- Sometimes, it's just not possible to transform a hypothesis function to be linear in terms of some parameters.
- In those cases, you'd have to resort to other methods of finding the optimal parameters.
 - For example, $H(x) = w_0 \sin(w_1 x)$ can't be transformed to be linear.
 - But, there are other methods of minimizing mean squared error:

$$R_{\text{sq}}(w_0, w_1) = \frac{1}{n} \sum_{i=1}^n (y_i - w_0 \sin(w_1 x))^2$$

- One method: **gradient descent**, the topic of the next lecture!
- Hypothesis functions that are linear in the parameters are much easier to work with.

Question 🤔

We want $H(x) = \sum_{i=0}^d w_i \square$
no w 's

Answer at q.dsc40a.com

Which hypothesis function is **not** linear in the parameters?

- A. $H(\vec{x}) = w_1 (x^{(1)} x^{(2)}) + \frac{w_2}{x^{(1)}} \sin(x^{(2)})$ $= w_1 \square + w_2 \square$
- B. $H(\vec{x}) = 2^{w_1} x^{(1)}$
- C. $H(\vec{x}) = \vec{w} \cdot \text{Aug}(\vec{x}) = w_0 + w_1 x^{(1)} + w_2 x^{(2)} + \dots$
- D. $H(\vec{x}) = w_1 \cos(x^{(1)}) + w_2 2^{x^{(2)}} \log x^{(3)}$ $=$
- E. More than one of the above.

→ we can apply transformation

Roadmap

- This is the end of the content that's in scope for the Midterm Exam.
- Now, we'll introduce **gradient descent**, a technique for minimizing functions that can't be minimized directly using calculus or linear algebra.
- After the Midterm Exam, we'll:
 - Switch gears to **probability**.

Lecture 14

Gradient Descent

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Agenda

- Minimizing functions using gradient descent.
- Convexity.
- More examples.
 - Huber loss.
 - Gradient descent with multiple variables.

Question 🤔

Answer at q.dsc40a.com

Remember, you can always ask questions at q.dsc40a.com!

If the direct link doesn't work, click the "🤔 Lecture Questions"
link in the top right corner of dsc40a.com.

The modeling recipe

1. Choose a model.

① $H(x) = h$ constant

② $H(x) = w_0 + w_1 x$
simple linear regression

③ $H(\vec{x}) = w_0 + w_1 x^{(1)} + w_2 x^{(2)} + \dots + w_d x^{(d)}$
 $= \vec{w} \cdot \text{Aug}(\vec{x})$
 $\vec{h} = X\vec{w}$

2. Choose a loss function.

Ⓐ squared loss $(y_i - H(x_i))^2$

Ⓒ 0-1 loss

Ⓑ absolute loss $|y_i - H(x_i)|$

3. Minimize average loss to find optimal model parameters.

empirical risk

①Ⓐ $R_{sq}(h) = \frac{1}{n} \sum (y_i - h)^2 \Rightarrow h^* = \text{mean}\{y_1, \dots, y_n\}$

③Ⓐ $R_{sq}(\vec{w}) = \frac{1}{n} \|y - X\vec{w}\|^2 = \|\vec{e}\|^2$

Minimizing functions using gradient descent

Minimizing empirical risk

- Repeatedly, we've been tasked with **minimizing** the value of empirical risk functions.
 - Why? To help us find the **best** model parameters, h^* or w^* , which help us make the **best** predictions!
- We've minimized empirical risk functions in various ways.

- $R_{\text{sq}}(h) = \frac{1}{n} \sum_{i=1}^n (y_i - h)^2$ calculus

- $R_{\text{abs}}(w_0, w_1) = \frac{1}{n} \sum_{i=1}^n |y_i - (w_0 + w_1 x)|$ python

- $R_{\text{sq}}(\vec{w}) = \frac{1}{n} \|\vec{y} - X\vec{w}\|^2$ linear algebra

Minimizing arbitrary functions

- Assume $f(t)$ is some **differentiable** single-variable function.
- When tasked with minimizing $f(t)$, our general strategy has been to:
 - ➔ i. Find $\frac{df}{dt}(t)$, the derivative of f .
 - ii. Find the input t^* such that $\frac{df}{dt}(t^*) = 0$.
- However, there are cases where we can find $\frac{df}{dt}(t)$, but it is **either difficult or impossible to solve** $\frac{df}{dt}(t^*) = 0$.

can't isolate t !

$$t^4 = \text{~~~~~}$$

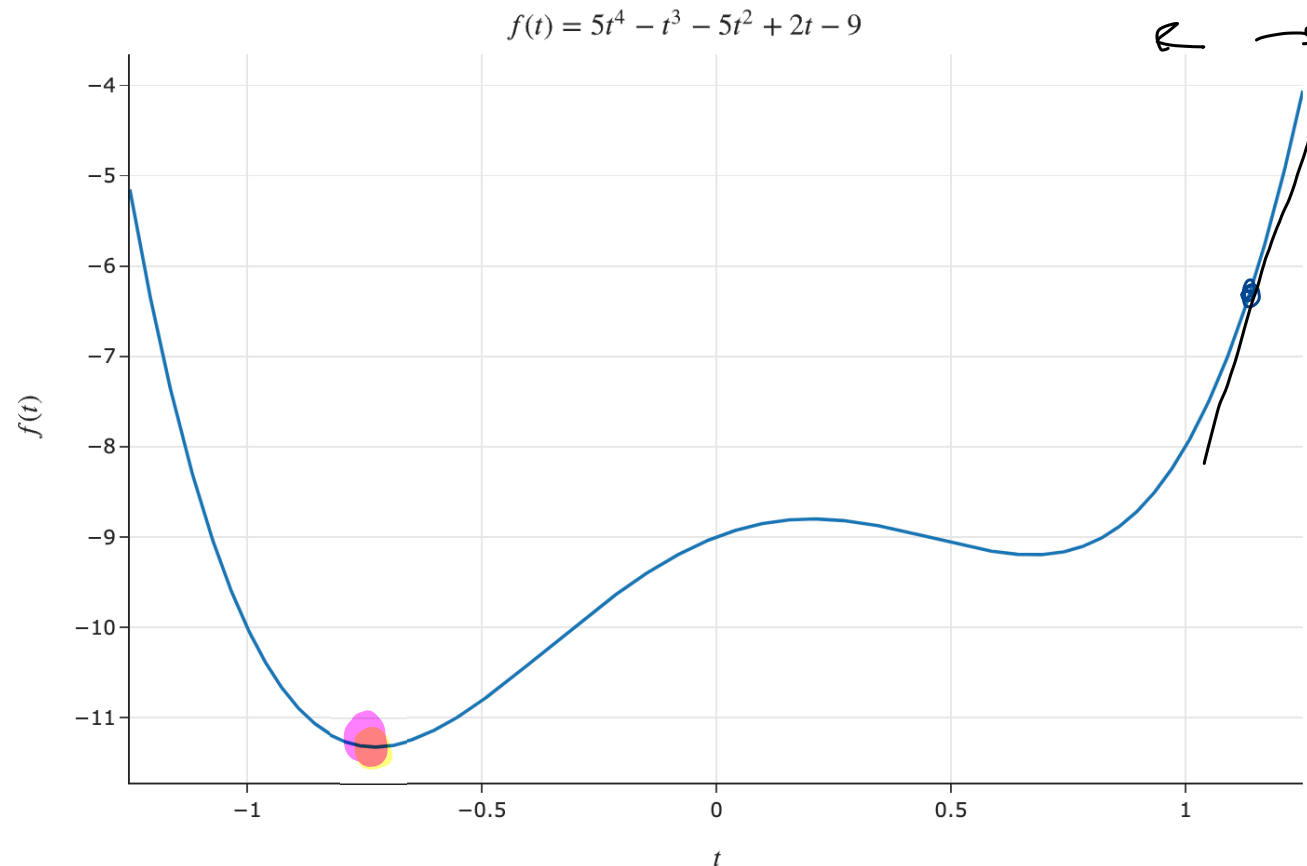
$$f(t) = 5t^4 - t^3 - 5t^2 + 2t - 9$$

$$\frac{df(t)}{dt} = 20t^3 - 3t^2 - 10t + 2$$

- Then what?

What does the derivative of a function tell us?

- **Goal:** Given a differentiable function $f(t)$, find the input t^* that minimizes $f(t)$.
- What does $\frac{d}{dt} f(t)$ mean?



Let's go hiking!

- Suppose you're at the top of a mountain 🏔️ and need to get to the bottom.
- Further, suppose it's really cloudy ☁️, meaning you can only see a few feet around you.
- **How** would you get to the bottom?

